

Conditional Value-at-Risk Based Approaches to Robust Network Flow, Connectivity and Design Problems

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Project Summary

- **Objective:** Develop models and algorithms for network flow, network design, and connectivity problems under uncertainty with the aim of obtaining robust solutions to the problems
- **Uncertainty:** Probabilistic node and arc failures modeled using uniform random graphs, random graphs of given expected degree sequence, and other models based on preferential attachment
- **Robustness:** By bounding or minimizing the conditional value-at-risk (CVaR) of an appropriately designed loss function, which quantifies losses as a function of decisions made under uncertainty
- **Problems investigated:** Minimum cost flows (including its special cases such as shortest paths, maximum flows, circulation), minimum spanning k -cores, minimum spanning r -robust k -clubs, and critical node detection
- **Research tasks:** Model development; theoretical study and algorithm design; large-scale implementation, testing and validation

Uncertainty in the network structure

- Underlying network is assumed to be uncertain; We assume that an edge exists with some probability quantified by random graph models of given expected degree sequence
- Given a sequence $w = (w_1, \dots, w_n)$, a random graph $G(w)$ is defined where the probability of an edge between $i, j \in V$ is given by:

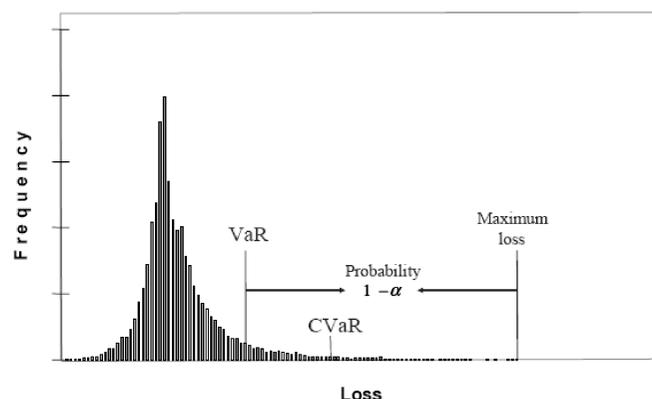
$$p_{ij} = \frac{w_i w_j}{\sum_{k \in V} w_k}$$
- Erdos-Renyi random graph model $G(n, p)$ is obtained from $G(w)$ by choosing $w_i = np$
- $G(w)$ represents a power-law random graph model when sequence w obeys a power-law
- Power-law model is particularly interesting as network models of many natural and engineered complex systems have been empirically shown to exhibit power-law degree distributions
- Models of preferential attachment, and duplication models describing power-law graphs will also be investigated

Robustness Via Conditional Value-at-Risk

- **Loss function:** Suppose $L(\mathbf{x}, \mathbf{Y})$ quantifies losses associated with decision vector \mathbf{x} and random vector \mathbf{Y} of uncertain parameters
- α -Value-at-Risk is the α -percentile of the distribution associated with the loss function which depends on \mathbf{x}

$$\alpha\text{-VaR}[L(\mathbf{x}, \mathbf{Y})] = \min\{q : P\{L(\mathbf{x}, \mathbf{Y}) \leq q\} \geq \alpha\}$$
- α -Conditional Value-at-Risk is the expectation of losses exceeding α -VaR, the mean of the α tail distribution of $L(\mathbf{x}, \mathbf{Y})$,

$$\alpha\text{-CVaR}[L(\mathbf{x}, \mathbf{Y})] = E[L(\mathbf{x}, \mathbf{Y}) | L(\mathbf{x}, \mathbf{Y}) \geq \alpha\text{-VaR}[L(\mathbf{x}, \mathbf{Y})]]$$



- A decision \mathbf{x} that minimizes (or limits) α -CVaR of $L(\mathbf{x}, \mathbf{Y})$ minimizes (or limits) the average losses in the worst $1-\alpha$ percentage of cases, and is considered a robust solution
- CVaR aggregates various losses under uncertainty into a single coherent measure of downside risk and is more conservative than VaR
- CVaR is convex in \mathbf{x} if $L(\mathbf{x}, \mathbf{Y})$ is convex in \mathbf{x} , which is desirable if CVaR is minimized or bounded from above, inside an optimization framework
- Explicit distribution for $L(\mathbf{x}, \mathbf{Y})$, explicit expression for CVaR, or computation of VaR are not needed, instead the following convex function can be used in place of CVaR:

$$F_\alpha(x, \zeta) = \zeta + \frac{1}{1-\alpha} E[(L(\mathbf{x}, \mathbf{Y}) - \zeta)^+]$$
- Since CVaR is an expectation, higher order moments can be used to quantify risk of losses under uncertainty for heavy tailed distributions

The Minimum Spanning k -Core Problem

- The proposed idea to employ CVaR to obtain robust solutions to optimization problems can be illustrated using a novel network design problem studied in this project, based on the concept of k -cores introduced by Seidman in 1983 for social network analysis

Definition (Seidman, 1983)

Given a simple undirected graph $G = (V, E)$, for $S \subseteq V$, the induced subgraph $G[S]$ is called a k -core if the minimum degree in $G[S]$ is at least k .

- One can add edges to the network (design it) so that it results in a k -core; Appropriate choice of parameter k can guarantee desired diameter and vertex connectivity; This leads to the minimum spanning k -core problem

Definition

Given $V = \{1, \dots, n\}$, c_{ij} for each distinct i, j pair and a fixed positive integer k , identify a minimum cost set of edges E^* to be created so that the graph $G = (V, E^*)$ is a k -core.

- The minimum spanning k -core problem is polynomial-time solvable using generalized graph matching techniques
- Suppose edges have probabilities of survival/failure, hence a spanning k -core could cease being one if some edges we chose, failed; Consider the loss function,

$$L(\mathbf{x}, \mathbf{Y}) = \sum_{v \in V} (k - \sum_{e \in \delta(v)} x_e Y_e)^+$$

which measures the cumulative degree deficiency under uncertainty where x_e is a binary variable indicating if e is chosen to be included, and Y_e is an indicator random variable for edge e surviving

- The CVaR constrained minimum spanning k -core problem under uncertainty can be formulated as:

Formulation (CVaR constrained)

$$\begin{aligned} \min \quad & \sum_{e \in E} c_e x_e \\ & \sum_{v \in V} x_e \geq k, v \in V \\ & \zeta + \frac{1}{1-\alpha} \sum_{s=1}^{|R|} p_s [(L(\mathbf{x}, \mathbf{y}^s) - \zeta)^+] \leq C \\ & \zeta \in \mathbb{R} \\ & x_e \in \{0, 1\}, e \in E \end{aligned}$$

- We expect to be able to develop a polynomial time separation algorithms since the original problem is polynomial time solvable; This is under investigation
- CVaR formulations of min cost flow problem and algorithms have been developed; In this case, the number of samples needed to estimate CVaR to desired accuracy is polynomial in the number of arcs