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Background

- ▶ Domain: atomic-level molecular dynamics
 - Classical MD: good scalable methods, but static bonding and fixed charges limit modeling capability
 - ▶ Reactive, polarizable MD: expand modeling ability but pose new computational challenges: dynamic charge distribution for reactivity
 - ▶ Idea: distribute charge (electrons) to atoms according to min. energy configuration (ground state)
- ► Goal: improve performance of expensive, poorly scaling charge distribution kernel
- ▶ Models for Charge Distribution:
 - ▶ charge equilibration (QEq)
 - electronegativity equilibration (EEM)
 - atom condensed Kohn-Sham DFT approximated to second order (ACKS2)
 - ▶ split charge equilibration (SQE)
 - others (active research)
- ▶ Approaches for Finding Charges in Models:
 - ▶ linear solvers: iterative (GMRES with preconditioning)
 - extended Lagrangian

QEq Overview

Minimize
$$\mathbf{E}_{ele}(\mathbf{Q}) = \sum_{i} \chi_i q_i + \frac{1}{2} \sum_{i,j} H_{ij} q_i q_j$$

where $H_{ij} = J_i \delta_{ij} + \frac{1 - \delta_{ij}}{\sqrt[3]{r_{ij}^3 + \gamma_{ij}^{-3}}}$
subject to $Q_{net} = \sum_{i} q_i$

After applying the Lagrange multiplier method:

$$-\chi_k = \sum_i H_{ki} s_i, \qquad k = 1, \dots, n$$
$$-1 = \sum_i H_{ki} t_i, \qquad k = 1, \dots, n$$

where:

$$q_i = s_i - \frac{\sum_i s_i}{\sum_i t_i} \cdot t_i$$

- ▶ $\mathbf{R} = (r_1, r_2, \dots, r_n)$: positions in system with *n* atoms ($\in \mathbb{R}^3$)
- ► $\mathbf{Q} = (q_1, q_2, \dots, q_n)$: partial charges (unknowns)
- χ_i : electronegativity of atom i
- J_i : idempotential of atom i
- ► $r_{ij} = ||r_j r_i||_2$: distance between atoms *i* and *j*
- γ : electrostatic shielding term

Preconditioner Design and Considerations

Design

- ▶ Idea: use good initial guesses (already done via extrapolation)
- ▶ Idea: apply preconditioning to GMRES residual vector
 - ▶ Relatively different than those for PDE discretizations: much higher NNZ per row on average

Considerations

- ▶ Effectiveness: reduction in num. of solver iters.
- ▶ Cost: computation and application time
- ▶ Longevity: num. of sim. iters. for which preconditioner is usable
- ▶ Parallelizabilty: shared mem. scalability of preconditioner
 - ▶ Important building block for dist. mem. algorithms!

Preconditioner Computation Methods

Basic Techniques

▶ Diagonal inverse (**Diag**)

$$\mathbf{P}_{ij}^{-1} = \begin{cases} \frac{1}{\mathbf{H}_{ij}}, & i = j\\ 0, & \text{otherwise} \end{cases}$$

- ▶ Incomplete factorizations with 0 fill-in
 - ► Cholesky with level scheduling (IC(0))
 - Idea: analyze sparsity pattern, perform parallel operations on independent levels

$$\mathbf{H}\approx \mathbf{U^T}\mathbf{U}$$

- ► Fine grained (**FG-ILU(0)**)
 - Idea: asynchronous constraint-based approach

 $\mathbf{H}\approx\mathbf{L}\mathbf{U}$

Preconditioner	\mathbf{Cost}	Longevity	Effectiveness	Parallelism
Diagonal	Very Low	High	Low	High
IC(0)	High	Moderate	High	Low
FG-ILU(0)	Very High	Moderate	High	High

Preconditioner Computation Methods

Enhanced Techniques

- Distance drop (IC-dist(d), FG-ILU-dist(d))
 - Insight: off-diagonal entries are inversely proportional to distance between atoms

 $r_{ij} > r_{\text{nonb}} \cdot d, \qquad d \in (0,1)$

- ► Dual drop (IC-dual(t), FG-ILU-dual(t))
 - Numeric thresholding based on row-wise 1-norm

$$H_{ij} > ||H_{i,:}||_1 \cdot t, \qquad t \in \mathbf{R}^+$$

 Apply during and post factor computation for IC-dual(t), but only post for FG-ILU-dual(t) to achieve convergence

Preconditioner Application Methods

Techniques for Incomplete Factorizations

- ▶ Level scheduling
 - Symbolic stage: find available parallelism in triangular solves (once per preconditioner computation)
 - ▶ Numeric stage: perform solves in parallel per level
 - ► Combine with IC(0), IC-*(*) computation methods
- ▶ Jacobi iteration
 - Approximate traingular solve:
 - To solve the triangular system Fx = b, instead iterate

$$x_{k+1} = (I - D^{-1}F) x_k + D^{-1}b$$

- ▶ Fixed num. of iters. (SpMV, vector-vector ops.)
- ► Combine with **FG-ILU(0)**, **FG-ILU-***(*) computation methods

Numeric Experiments

Setup

- \blacktriangleright Platform
 - ▶ NERSC Edison: Cray XC30
 - ▶ 12-core Intel Ivy Bridge, 2.4 GHz (dual socket)
 - Private L1 (32 KB inst., 32 KB data), L2 (256 KB) caches
 - Shared 30 MB L3
 - ▶ 64 GB DDR3, 1866 MHz bus
- ▶ Software and Tools
 - PuReMD ReaxFF
 - ▶ Intel compiler v15.0.1
 - Optimization flags: -fast

► Chemical Systems

Name	Chemical Formula	$\# \mathbf{Atoms}$	Type
Water	H_2O	$78,\!480$	Liquid
Silica	SiO_2	72,000	Amorphous material
PETN	$C_5 H_8 N_4 O_{12}$	48,256	Perfect crystal
Bilayer	Phospholipid bilayer	56,800	Soft matter

Numeric Experiments

 ${\rm Cost-Effectiveness}\ {\rm Trade-off}$



Figure: Effectiveness vs. expected cost of various preconditioned GMRES solvers (averaged across all four benchmark systems)

Numeric Experiments

Longevity



Figure: **FG-ILU-dual(0.01)** for the bulk water system, 100 steps before re-computing preconditioner

Numeric Experiments

Overall Solver Performance



Figure: Average QEq times for different solvers, numbers over each bar group show the speedup achieved by the IC-dual scheme over the Diag solver

Numeric Experiments Thread Scalability

Figure: IC-dual(0.01) with water (left) and PETN (right) at solver tol. 10^{-14}



Table: Num. of levels in preconditioner factors

System	IC(0)	IC-dual(0.01)	IC-dist(0.8)	IC-dist(0.6)
Bilayer	4921	711	3280	1851
PETN	13181	13181	39078	16003
Silica	10799	634	6147	1705
Water	25479	1769	12365	5142

Future Work and Acknowledgements

Future Work

- ▶ Reduce num. levels and sync. of PreApp through explicit permutations via graph coloring
- ► Experiment with further combinations of enhanced preconditioning techniques
- ▶ Implement approaches on many-core architectures (Xeon Phi)
- ▶ Develop an automated parameter tuning method

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