New Analysis

Low-Rank Incremental Methods for Computing Dominant Singular Subspaces

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- Overview of Low-Rank Methods
- Operation of Low-Rank Methods

- Link to Iterative Eigensolvers
- Multi-pass Approaches

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Introduction

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The Singular Va	lue Decomposition		
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Definition

The singular value decomposition of an $m \times n$ matrix A is

$$A = U\Sigma V^{T} = \begin{bmatrix} U_{1} & U_{2} \end{bmatrix} \begin{bmatrix} \Sigma \\ 0 \end{bmatrix} V^{T} = U_{1}\Sigma V^{T}$$

with orthogonal $U, V; \Sigma$ diagonal with non-decreasing, non-negative entries.

Terminology

The columns of U_1 and V are left and right singular vectors. Diagonal entries of Σ are singular values. Largest singular values are dominant, as are their corresponding singular vectors.

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Dominant SVD					

Applications

Many applications require only the dominant singular triplets, e.g., PCA, KLT, POD.

Computation

Numerous approaches for computing the dominant SVD:

- compute the full SVD and truncate the unneeded part;
- transform to an eigenvalue problem, compute relevant eigenvectors via iterative eigensolver, back-transform;
- use iterative solver to compute dominant SVD:
 - Riemannian optimization gives many approaches [ABG2007]
 - Non-linear equation \rightarrow JD-SVD [Hochstenbach2000]
 - Low-rank incremental methods

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Incremental	SVD		

Motivation

In many applications, the production of the matrix *A* happens incrementally. This has motivated numerous methods for SVD updating. [e.g., Businger; Bunch,Nielson]

Benefits

- Latency in producing new columns of *A* can be amortized in the SVD update
- "Online" SVD is useful/necessary in some applications

Drawbacks

- Computation, storage is expensive
- Still computes the full SVD

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Low-Rank Inc	remental SVD		

More efficient approach

The low-rank incremental SVD methods follow the example of the incremental SVD methods, but track only a low-dimensional subspace.

History

Repeatedly and independently described in the literature:

- 1995: Manjunath, Chandrasekaran, Yang: "Eigenspace Update Algorithm"
- 2000: Levy, Lindenbaum: "Sequential Karhunen-Loeve"
- 2001: Chahlaoui, Gallivan, Van Dooren: "Recursive SVD"
- 2002: Brand: "Incremental SVD"
- 2004: Baker, Gallivan, Van Dooren

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Kernel Step

Given a matrix A with factorization $A = U\Sigma V^T$, compute updated factorization of augmented matrix $\begin{bmatrix} A & A_+ \end{bmatrix}$:

$$U_{+}\Sigma_{+}V_{+}^{T} = \begin{bmatrix} A & A_{+} \end{bmatrix} = \begin{bmatrix} U\Sigma V^{T} & A_{+} \end{bmatrix}$$

Incremental Algorithm

- Partition $A = \begin{bmatrix} A_1 & A_2 & \dots & A_b \end{bmatrix}$
- Initialize $A_1 = U_1 \Sigma_1 V_1^T$
- for i = 2, ..., b
 - Update factorization:

$$U_i \Sigma_i V_i^T = \begin{bmatrix} U_{i-1} \Sigma_{i-1} V_{i-1}^T & A_i \end{bmatrix}$$

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Low-rank Incren	nental SVD Operation		
• Perform	a low-rank version of the incr	remental SVD	
Kernel Step			

Given a factorization $U\Sigma V^T$ and columns A_+ , compute dominant SVD $U_+\Sigma_+V_+^T \approx \begin{bmatrix} U\Sigma V^T & A_+ \end{bmatrix}$.

Heuristic motivation

Approximation of an approximation is an approximation, right?

$$U_{1}\Sigma_{1}V_{1}^{T} \approx A_{1}$$

$$U_{2}\Sigma_{2}V_{2}^{T} \approx \begin{bmatrix} U_{1}\Sigma_{1}V_{1}^{T} & A_{2} \end{bmatrix} \approx \begin{bmatrix} A_{1} & A_{2} \end{bmatrix}$$

$$\dots$$

$$U_{b}\Sigma_{b}V_{b}^{T} \approx A$$

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The algorithm

Given the factorization $U\Sigma V^T$ and new columns *A*:

Expand the factorization via Gram-Schmidt:

$$\begin{bmatrix} U\Sigma V^T & A \end{bmatrix} = \hat{Q}\hat{R}\hat{W}^T \doteq \begin{bmatrix} U & Q \end{bmatrix} \begin{bmatrix} \Sigma & R_2 \\ 0 & R_3 \end{bmatrix} \begin{bmatrix} V & 0 \\ 0 & I \end{bmatrix}^T$$

2 Compute transformations G_u, G_v that decouple the singular subspaces in \hat{R} :

$$G_u^T \hat{R} G_v = \begin{bmatrix} ar{R}_1 & 0 \\ 0 & ar{R}_2 \end{bmatrix}, \qquad \sigma(ar{R}_1) > \sigma(ar{R}_2)$$

- 3 Insert G_u, G_v into expanded factorization: $\bar{Q}\bar{R}\bar{W}^T \doteq (\hat{Q}G_u)(G_u^T\hat{R}G_v)(G_v^T\hat{W}^T) = \hat{Q}\hat{R}\hat{W}^T$
- Truncate the dominated part of the factorization.

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Cost/benefit

Benefits:

- Requires only a single pass through A
- Exploits latency in producing/retrieving columns of A
- Flop count is linear: O(mnk)
 - Leading coefficient varies according to requirements on structure of intermediate factorizations
 - Method from [Baker2004] requires 10mnk flops
- Storage of O(mk + nk) is minimal

Drawback:

- Factorization is inexact due to truncation
- Previous literature makes no suggestion for improving factorization

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What is really h	appening?				
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New interpretation

Take an orthogonal matrix $D = \begin{bmatrix} D_1 & \dots & D_b \end{bmatrix}$. Consider the low-rank incremental SVD of $AD = \begin{bmatrix} AD_1 & \dots & AD_b \end{bmatrix}$.

A locally optimal solver

At iterate U_i , Σ_i , V_i , the algorithm inputs AD_{i+1} and chooses V_{i+1} which maximizes *trace* $\begin{pmatrix} V^T A^T A V \end{pmatrix}$ over all orthonormal V in span $(\begin{bmatrix} V_i & D_{i+1} \end{bmatrix})$.

Implications

- IncSVD of A (i.e., D = I) implicitly performs coordinate ascent, optimization-based eigensolve of $A^{T}A$
- Choice of *D* gives a hook to affect the performance.

Multi-pass Method				
Multi-pass Approaches				
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Targeted initialization

- Given approximate right singular vectors \hat{V} , choose *D*: $D = \begin{bmatrix} \hat{V} & D_2 & \dots & D_b \end{bmatrix}$
- Use to restart the algorithm if *A* is still available.
- Can be done in a pass-efficient manner.

Better choices for D?

- If D_i is exact dominant right singular vectors, then incremental algorithm is exact.
- Speedup convergence by inserting gradient information into *D*.

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- The decoupling technique makes explicit the effort necessary to implement a member of this family of methods.
- The novel analysis shows the link to an iterative, optimization-based eigensolver approach.
- This analysis allows the description of methods which can exploit multiple passes through *A*.
- Convergence proof with rate of convergence is forthcoming.
- "Killer apps" wanted.