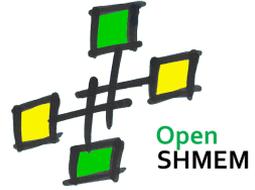


Latest in OpenSHMEM: Specification, API, and Programming

Presenters:

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Tutorial Outline



- The OpenSHMEM API
- Solving SAT with OpenSHMEM
- OpenSHMEM Serial to Parallel Code
Distributed Hash Table
- OpenSHMEM implementation: from the hardware layer to the user layer

The OpenSHMEM API

Graham Lopez
ORNL

Material: Swaroop Pophale

Outline

- Background
- Introduction to OpenSHMEM
- History of SHMEM
- OpenSHMEM Effort
- OpenSHMEM Concepts
- OpenSHMEM API

We assume ...

- Knowledge of C
- Familiarity with parallel computing
- Linux/UNIX command-line

Background

- Global vs. distributed Address Spaces
 - OpenMP has global (shared) space
 - MPI has partitioned space; private data exchanged via messages
 - OpenSHMEM uses “partitioned global address space” (PGAS)
 - Implemented as a library

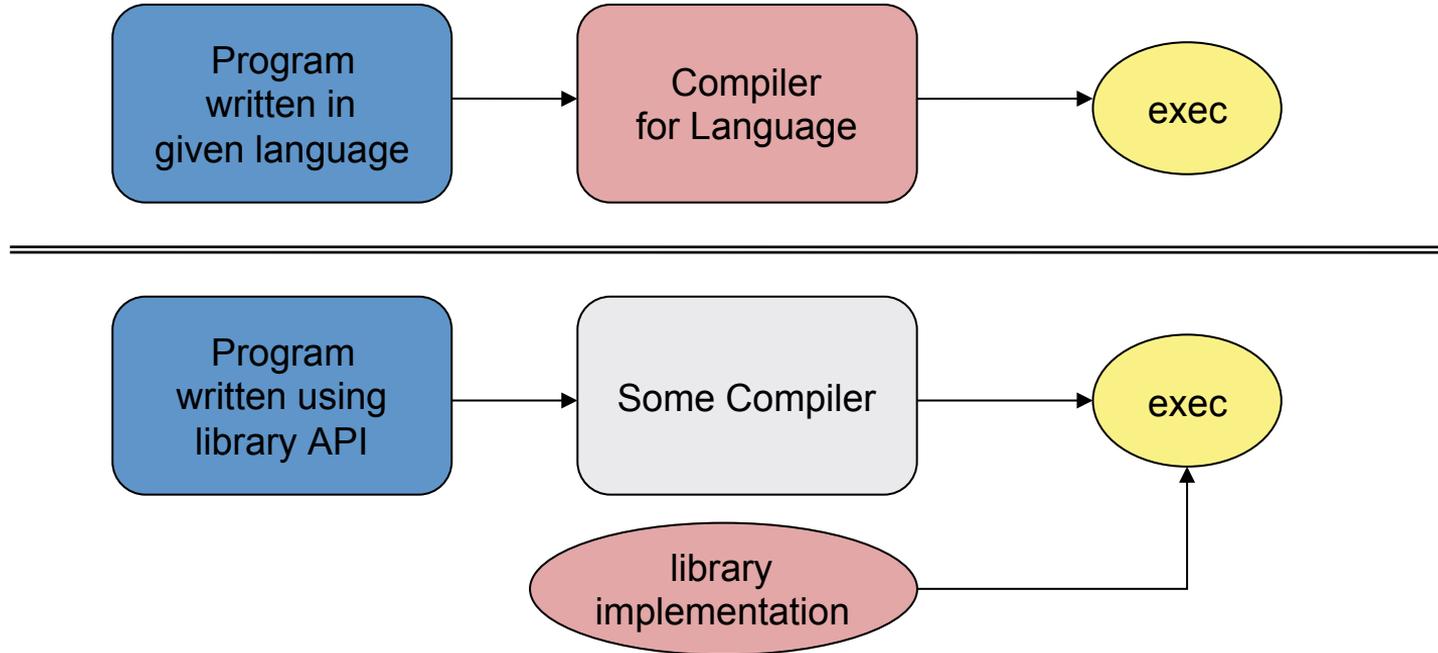
Background

- SPMD – single program, multiple data
 - Program launches many processes
 - Each starts with the same code (SP)
 - But then typically operates on some specific part of the data (MD)
 - Processes may then communicate with each other
 - Share common data
 - Broadcast work
 - Collect results
 - Synchronization

Background

- The PGAS family
 - Libraries include:
 - GASNet, ARMCI / Global Arrays, UCCS, CCI, GASPI/GPI, OpenSHMEM
 - Languages include:
 - Chapel, Titanium, X10, UPC, CAF
- A language or library can be used on many machine types, their implementation hides differences & leverages features

Background



PGAS Languages vs Libraries

Background

Languages	Libraries
Often more concise	More information redundancy in program
Requires compiler support	Generally not dependent on a particular compiler
More compiler optimization opportunities	Library calls are a "black box" to compiler, typically inhibiting optimization
User may have less control over performance	Often usable from many different languages through bindings
Examples: UPC, CAF, Titanium, Chapel, X10	Examples: OpenSHMEM, Global Arrays, MPI-3

PGAS Languages vs Libraries

Background

PGAS Language - UPC

- A number of threads working independently in an SPMD fashion
- Number of threads specified at compile-time or run-time; program variable `THREADS`
 - `MYTHREAD` specifies thread index ($0..THREADS-1$)
 - `upc_barrier` is a global synchronization: all wait
 - `upc_forall` is the work sharing construct
- There are two compilation modes
 - Static and Dynamic threads mode

Background

Hello World in UPC

- Any legal C program is also a legal UPC program
- If you compile and run it as UPC with N threads, it will run N copies of the program.
- Example of a parallel hello world using UPC:

```
#include <upc.h> /* needed for UPC extensions */
#include <stdio.h>

main() {
    printf("Thread %d of %d: hello UPC world\n",
          MYTHREAD, THREADS);
}
```

Background

- PGAS Language - Coarray Fortran (CAF)
 - Multiple executing images
 - Explicit data decomposition and movement across images achieved by declaring and accessing coarrays
 - Image control statements
 - subdivide program into execution segments
 - determine partial ordering of segments among images
 - define scope for compiler optimization
 - Part of Fortran 2008 standard
 - Other languages enhancements (teams, expanded collectives and atomics, semaphore synchronization, resilience) are being considered for next revision

Introduction to OpenSHMEM

- An SPMD parallel programming library
 - Library of functions similar in feel to MPI (e.g. `shmem_get()`)
- Available for C / Fortran
- Used for programs that
 - perform computations in separate address spaces and
 - explicitly pass data to and from different processes in the program.
- The processes participating in shared memory applications are referred to as processing elements (PEs).
- OpenSHMEM routines supply remote data transfer, work-shared broadcast and reduction, barrier synchronization, and atomic memory operations.

Introduction to OpenSHMEM

- An OpenSHMEM “Hello World”

```
#include <stdio.h>
#include <shmem.h>

int main (int argc, char **argv) {
    int me, npes;
    shmem_init (); /*Library Initialization*/
    me = shmem_my_pe ();
    npes = shmem_n_pes ();
    printf ("Hello World from PE %4d of %4d\n", me, npes);
    return 0;
}
```

History of SHMEM

- Cray
 - SHMEM first introduced by Cray Research Inc. in 1993 for Cray T3D
 - Platforms: Cray T3D, T3E, PVP, XT series
 - SGI
 - Owns the “rights” for SHMEM
 - Baseline for OpenSHMEM development (Altix)
 - Quadrics (company out of business)
 - Optimized API for QsNet
 - Platform: Linux cluster with QsNet interconnect
 - Others
 - HP SHMEM, IBM SHMEM
 - GP SHMEM (cluster with ARMCI & MPI support, old)
- Note: SHMEM was not defined by any one standard.

Divergent Implementations

- Many forms of initialization
 - Include header shmem.h to access the library
 - `#include <shmem.h>`
 - `#include <mpp/shmem.h>`
 - `start_pes`, `shmem_init`: Initializes the shmem portion of the program
 - `my_pe`: Get the PE ID of local processor
 - `num_pes`: Get the total number of PEs in the system

Divergent Implementations

SGI		Quadrics	Cray	
Fortran	C/C++	C/C++	Fortran	C/C++
start_pes	start_pes(0)	shmem_init	start_pes	start_pes
			shmem_init	shmem_init
shmem_my_pe	shmem_my_pe		shmem_my_pe	shmem_my_pe
shmem_n_pes	shmem_n_pes		shmem_n_pes	shmem_n_pes
NUM_PES	num_pes	num_pes	NUM_PES	
MY_PE	my_pe	my_pe		

Divergent Implementations

Hello World (SGI on Altix)

```
#include <stdio.h>
#include <mpp/shmem.h>
int main(void)
{
    int me, npes;
    start_pes(0);
    npes = _num_pes();
    me = _my_pe();
    printf("Hello from %d of %d\n",
           me, npes);
    return 0;
}
```

Hello World (Cray)

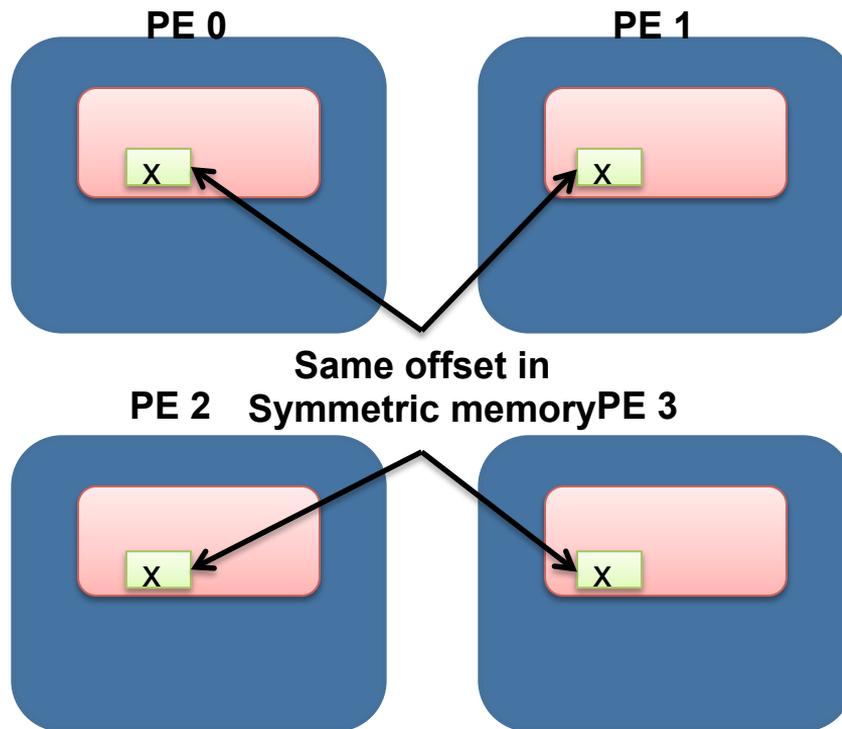
```
#include <stdio.h>
#include <shmem.h>
int main(void)
{
    int me, npes;
    shmem_init();
    npes = num_pes();
    me = my_pe();
    printf("Hello from %d of %d\n",
           me, npes);
    return 0;
}
```

OpenSHMEM Concepts

- Symmetric Variables
 - Arrays or variables that exist with the **same name, size, type, and relative address** on all PEs.
 - The following kinds of data objects are symmetric:
 - Fortran data objects in common blocks or with the **SAVE** attribute.
 - Non-stack C and C++ variables.
 - Fortran arrays allocated with **shpalloc**
 - C and C++ data allocated by **shmalloc**

OpenSHMEM Concepts

```
int main (void)
{
    int *x;
    ...
    shmem_init();
    ...
    x = (int*)
    shmalloc(sizeof(*x));
    ...
    shmem_barrier_all();
    ...
    shfree(x);
    return 0;
}
```



Dynamic allocation of Symmetric Data

OpenSHMEM API

- Initialization, Query and Exit Routines
- Memory Management Routines
- Data transfers
- Synchronization mechanisms
- Collective communication
- Atomic Memory Operations

OpenSHMEM Initialization, Query and Exit

void shmem_init(void)

- Same functionality as deprecated `void start_pes(int n)`
- Number of PEs taken from invoking environment
 - E.g. from MPI or job scheduler
- PEs numbered 0 .. (N – 1) in flat space

int shmem_n_pes(void)

- return number of PEs in this program

int shmem_my_pe(void)

- return “rank” of calling PE

void shmem_finalize(void)

- collective operation to exit the OpenSHMEM environment

void shmem_global_exit(int status)

- one PE may force all PEs to exit the OpenSHMEM environment

OpenSHMEM Memory Management Routines

`void *shmem_malloc(size_t size)`

- Allocate symmetric memory on all PEs.

`void *shmem_free(void *ptr)`

- Deallocate symmetric memory.

`void *shmem_realloc(void *ptr, size_t size)`

- Resize the symmetric memory

`void *shmem_align(size_t alignment, size_t size)`

- Allocate symmetric memory with alignment

OpenSHMEM Memory Management Routines

```
/* shmem_alloc() & shmem_free() */
#include <stdio.h>
#include <shmem.h>
int main (int argc, char **argv)
{
    int *v;
    shmem_init();
    v=(int *)shmem_malloc(sizeof(int));
    ...
    ...
    shmem_free(v);
    return 0;
}
```

OpenSHMEM Accessibility

- `int shmem_pe_accessible(int pe)`
 - Can this PE talk to the given PE?
- `int shmem_addr_accessible(void *addr, int pe)`
 - Can this PE address the named memory location on the given PE?
- In SGI SHMEM used for mixed-mode MPI/SHMEM programs
 - In “pure” OpenSHMEM, could just return “1”
- Could in future be adapted for fault-tolerance

OpenSHMEM Data Transfer

- Put
 - Single variable
 - `void shmem_TYPE_p(TYPE *target, TYPE value, int pe)`
 - TYPE = double, float, int, long, short
 - Contiguous object
 - `void shmem_TYPE_put(TYPE *target, const TYPE *source, size_t nelems, int pe)`
 - For C: TYPE = double, float, int, long, longdouble, longlong, short
 - For Fortran: TYPE = complex, integer, real, character, logical
 - `void shmem_putN(void *target, const void *source, size_t nelems, int pe)`
 - Storage Size (N bits) = 32, 64, 128, mem (any size)

Target must be symmetric

OpenSHMEM Data Transfer

- Example: Cyclic communication via puts

```
/*Initializations*/
int src;
int *dest;
...
shmem_init();
...
src = me;
dest = (int *) shmem_malloc (sizeof (*dest));
nextpe = (me + 1) % npes; /*wrap around */

shmem_int_put (dest, &src, 1, nextpe);
...
shmem_barrier_all();
x = dest * 0.995 + 45 * y;
...
```

Points To Remember

- 'Destination' has to be symmetric
- Consecutive puts are not guaranteed to finish in order
- Put returns after the data has been copied out of the source
- Completion guaranteed only after synchronization

OpenSHMEM Data Transfer

- Get
 - Single variable
 - `TYPE shmем_TYPE_g(TYPE *target, TYPE value, int pe)`
 - For C: TYPE = double, float, int, long, longdouble, longlong, short
 - For Fortran: TYPE=complex, integer, real, character, logical
 - Contiguous object
 - `void shmем_TYPE_get(TYPE *target, const TYPE *source, size_t nelems, int pe)`
 - For C: TYPE = double, float, int, long, longdouble, longlong, short
 - For Fortran: TYPE=complex, integer, real, character, logical
 - `void shmем_getN(void *target, const void *source, size_t nelems, int pe)`
 - Storage Size (N bits) = 32, 64, 128, mem (any size)
- Source must be symmetric data object

OpenSHMEM Data Transfer

- Example: Summation at PE 0

```
/*Initializations*/
int *src, dest, sum;
...
shmem_init();
...
src = (int *) shmem_malloc (sizeof (*src));
src = me; sum = me;
if(me == 0){
    for(int i = 1; i < num_pes(); i++){
        shmem_int_get(&dest, src, 1, i)
        sum = sum + dest;
    }
}
...
```

Points To Remember

- ‘Source’ has to be remotely accessible
- Consecutive gets finish in order
- The routines return after the data has been delivered to the ‘dest’ on the local PE

OpenSHMEM Data Transfer

- Strided put/get

- `void shmem_TYPE_iput(TYPE *target, const TYPE *source, ptrdiff_t tst, ptrdiff_t sst, size_t nelems, int pe)`

- For C: TYPE = double, float, int, long, longdouble, longlong, short
 - For Fortran: TYPE=complex, integer, real, character, logical
 - tst and sst indicate stride between accesses of target and source resp.

OpenSHMEM Data Transfer

```
int main()
{
    static short source[10] = {1, 2, 3, 4, 5, 6, 7, 8, 9, 10};
    short target[10];
    int i, me;
    for (i = 0; i < 10; i += 1) {
        target[i] = 666;
    }
    shmem_init();
    me = _my_pe ();
    if (me == 1){
        /* source[0,1,2,3] -> target[0,2,4,6] */
        shmem_short_iget (target, source, 2, 1, 4, 0);
    }
    shmem_barrier_all ();    /* sync sender and receiver */
    if (me == 1){
        for (i = 0; i < 10; i += 1){
            printf ("PE %d: target[%d] = %hd, source[%d] = %hd\n",
                    me, i, target[i], i, source[i]);
        }
    }
    shmem_barrier_all ();    /* sync before exiting */
    return 0;
}
```

Output:

```
PE 1: target[0] = 1, source[0] = 1
PE 1: target[1] = 666, source[1] = 2
PE 1: target[2] = 2, source[2] = 3
PE 1: target[3] = 666, source[3] = 4
PE 1: target[4] = 3, source[4] = 5
PE 1: target[5] = 666, source[5] = 6
PE 1: target[6] = 4, source[6] = 7
PE 1: target[7] = 666, source[7] = 8
PE 1: target[8] = 666, source[8] = 9
PE 1: target[9] = 666, source[9] = 10
```

OpenSHMEM Data Transfer

- Put vs. Get
 - Put call completes when data is “being sent”
 - Get call completes when data is “stored locally”
- Cannot assume put has written until later synchronization
 - Data still in transit
 - Partially written at target
 - Put order changed by e.g. network
- Puts allow overlap
 - Communicate
 - Compute
 - Synchronize

OpenSHMEM Synchronization

- Active Sets
 - Way to specify a subset of PEs
 - A triplet:
 - Start PE
 - Stride (log2)
 - Size of set
- Limitations
 - Stride must be powers of 2
 - Only define 'regular' PE sub-groups

OpenSHMEM Synchronization

- Barrier (Group synchronization)
 - `void shmem_barrier_all()`
 - Suspend PE execution until all PEs call this function
 - `void shmem_barrier(int PE_start, int PE_stride, int PE_size, long *pSync)`
 - Barrier operation on subset of PEs
- pSync is a symmetric work array that allows different barriers to operate simultaneously

OpenSHMEM Synchronization

- Conditional wait (P2P synchronization)
 - Suspend until local symmetric variable NOT equal to the value specified
 - `void shmem_wait(long *var, long value)`
 - `void shmem_TYPE_wait(TYPE *var, TYPE value)`
 - For C: TYPE = int, long, longdouble, longlong, short
 - For Fortran: TYPE = complex, integer, real, character, logical
- Specific conditional wait
 - Similar to the generic wait except the comparison can now be
 - `>=`, `>`, `=`, `!=`, `<`, `<=`
 - `void shmem_wait_until(long *var, int cond, long value)`
 - `void shmem_TYPE_wait_until(TYPE *var, int cond, TYPE value)`
 - TYPE = int, long, longlong, short

OpenSHMEM Synchronization

```
#define GREEN 1
#define RED 0

int light=RED;
int main(int argc, char **argv)
{
    int me;
    shmem_init();
    me = shmem_my_pe();
    if(me==0){
        printf("me:%d. Stop on Red Light\n", me);
        shmem_int_wait(&light, RED); /* Is the light still red? */
        printf("me:%d. Now I may proceed\n", me);
    }
    if(me==1){
        sleep(1);
        light=GREEN;
        printf("me:%d. I've turn light to green.\n", me);
        shmem_int_put(&light, &light, 1, 0);
    }
    return 0;
}
```

Output:
me:0. Stop on Red Light
me:1. I've turned light to green
me:0. Now I may proceed

OpenSHMEM Synchronization

- `void shmem_fence()`
 - Ensures ordering of outgoing write operations on a per-PE basis.
- `void shmem_quiet()`
 - Waits for completion of all outstanding remote writes and stores to symmetric data objects initiated from the calling PE.

OpenSHMEM Synchronization

Example Fence

```
...
if (shmem_my_pe() == 0) {
shmem_long_put(target, source, 3, 1); /*put1*/
shmem_long_put(target, source, 3, 2); /*put2*/
    shmem_fence();
shmem_int_put(&targ, &src, 1, 1);      /*put3*/
shmem_int_put(&targ, &src, 1, 2);      /*put4*/
}
...
```

put1 will be **ordered** to be delivered before put3
put2 will be **ordered** to be delivered before put4

Example Quiet

```
...
shmem_long_put(target, source, 3, 1); /*put1*/
shmem_int_put(&targ, &src, 1, 2);      /*put2*/
    shmem_quiet();
shmem_long_get(target, source, 3, 1);
shmem_int_get(&targ, &src, 1, 2);
printf("target: {%d,%d,%d}\n",
        target[0], target[1], target[2]);
printf("targ: %d\n", targ); /*targ: 90*/
shmem_int_put(&targ, &src, 1, 1);      /*put3*/
shmem_int_put(&targ, &src, 1, 2);      /*put4*/
...
put1 & put2 will be delivered when quiet returns
```

OpenSHMEM Collective Communication

- Broadcast

- One-to-all symmetric communication
- No update on root

- `void shmem_broadcastN(void *target, void *source,
 size_t nelems, int PE_root,
 int PE_start, int PE_stride,
 int PE_size, long *pSync)`
Storage Size (N bits) = 32, 64

OpenSHMEM Collective Communication

```
...  
int *target, *source;  
target = (int *) shmalloc( sizeof(int) );  
source = (int *) shmalloc( sizeof(int) );  
*target = 0;  
if (me == 0) {  
    *source = 222;  
}  
else  
    *source = 101;  
shmem_barrier_all();  
shmem_broadcast32(target, source, 1, 0, 0, 0, 4, pSync);  
  
printf("target on PE %d is %d\n", shmem_my_pe(), *target);  
...
```

Code snippet showing working of shmem_broadcast

Output:

```
target on PE 0 is 0  
target on PE 1 is 222  
target on PE 2 is 222  
target on PE 3 is 222
```

OpenSHMEM Collective Communication

- Collection
 - Concatenates blocks of symmetric data from multiple PEs to an array in every PE
 - Each PE can contribute different amounts
 - `void shmem_collectN(void *target, void *source, size_t nelems, int PE_start, int PE_stride, int PE_size, long *pSync)`
- **Storage Size (N bits) = 32, 64**
- Concatenation written on all participating PEs
- `shmem_fcollect` variant
 - When all PEs contribute exactly same amount of data
 - PEs know exactly where to write data, so no offset lookup overhead

OpenSHMEM Collective Communication

```
int sum;
int me, npe;
int main(int argc, char **argv)
{
    int i;
    long *pSync;
    int *pWrk, pWrk_size;
    shmem_inti();
    me = shmem_my_pe();
    npe = shmem_n_pes();
    pWrk = (int *) shmalloc (npe);
    pSync = (long *) shmalloc (SHMEM_REDUCE_SYNC_SIZE);
    for (i = 0; i < SHMEM_REDUCE_SYNC_SIZE; i += 1){
        pSync[i] = _SHMEM_SYNC_VALUE;
    }
    shmem_barrier_all();
    shmem_int_sum_to_all(&sum, &me, 1, 0, 0, npe, pWrk, pSync);
    shmem_barrier_all();
    printf("me:%d. Total sum of 'me' is %d\n", me, sum);
    return 0;
}
```

Output:

```
me:1. Total sum of 'me' is 45
me:2. Total sum of 'me' is 45
me:3. Total sum of 'me' is 45
me:4. Total sum of 'me' is 45
me:5. Total sum of 'me' is 45
me:6. Total sum of 'me' is 45
me:7. Total sum of 'me' is 45
me:8. Total sum of 'me' is 45
me:9. Total sum of 'me' is 45
me:0. Total sum of 'me' is 45
```

OpenSHMEM Collective Communication

- Reductions
 - Perform commutative operation across symmetric data set
 - `void shmem_TYPE_OP_to_all(TYPE *target, TYPE *source, int nreduce, int PE_start, int PE_stride, int PE_size, TYPE *pWrk, long *pSync)`
 - Logical OP = and, or, xor
 - Extrema OP = max, min
 - Arithmetic OP = prod(uct), sum
 - TYPE = int, long, longlong, longdouble, short, complex
 - Reduction performed and stored on all participating PEs
 - pWrk and pSync allow interleaving
- E.g. compute arithmetic mean across set of PEs
 - `sum_to_all / PE_size`

OpenSHMEM Atomic Operations

- What does “atomic” mean anyway?
 - Indivisible operation on symmetric variable
 - No other operation can interpose during update
- But “no other operation” actually means...?
 - No other atomic operation
 - Can’t do anything about other mechanisms interfering
 - E.g. thread outside of OpenSHMEM program
 - Non-atomic OpenSHMEM operation
 - Why this restriction?
 - Implementation in hardware

OpenSHMEM Atomic Operations

- Atomic Swap
 - Unconditional
 - `long shmem_swap(long *target, long value, int pe)`
 - `TYPE shmem_TYPE_swap(TYPE *target, TYPE value, int pe)`
 - TYPE = double, float, int, long, longlong
 - Return old value from symmetric target
 - Conditional
 - `TYPE shmem_TYPE_cswap(TYPE *target, TYPE cond, TYPE value, int pe)`
 - TYPE = int, long, longlong
 - Only if “cond” matches value on target

OpenSHMEM Atomic Operations

- Arithmetic
 - increment (= add 1) & add value
 - `void shmem_TYPE_inc(TYPE *target, int pe)`
 - `void shmem_TYPE_add(TYPE *target, TYPE value, int pe)`
 - TYPE = int, long, longlong
 - Fetch-and-increment & fetch-and-add value
 - `TYPE shmem_TYPE_finc(TYPE *target, int pe)`
 - `TYPE shmem_TYPE_fadd(TYPE *target, TYPE value, int pe)`
 - TYPE = int, long, longlong
 - Return previous value at target on PE

OpenSHMEM Atomic Operations

```
...
long *dest;
dest = (long *) shmalloc( sizeof(*dest) );
  *dest = me;
  shmem_barrier_all();
...
new_val = me;
  if (me == 1) {
    swapped_val = shmem_long_swap(target, new_val, 0);
    printf("%d: target = %d, swapped = %d\n",
           me, *target, swapped_val);
  }
shmem_barrier_all();
...
```

OpenSHMEM Atomic Operations

- Locks
 - Symmetric variables
 - Acquired and released to define mutual-exclusion execution regions
 - Only 1 PE can enter at a time
 - `void shmem_set_lock(long *lock)`
 - `void shmem_clear_lock(long *lock)`
 - `int shmem_test_lock(long *lock)`
 - Acquire lock if possible, return whether or not acquired
 - But don't block...
 - Initialize lock to 0. After that managed by above API
 - Can be used for updating distributed data structures

Solving SAT with OpenSHMEM

Pavel Shamis
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Background

The examples are based on <http://ubcsat.dtompkins.com>

- Code <https://github.com/dtompkins/ubcsat>
- OpenSHMEM based code
<https://github.com/shamisp/ubcsat/tree/shmem>

Parallel solver algorithm is based on: “*Massively Parallel Local Search for SAT*”, Alejandro Arbelaez, Philippe Codognet

- Full paper:
<http://ieeexplore.ieee.org/xpl/login.jsp?tp=&arnumber=6495029&url=http%3A%2F%2Fieeexplore.ieee.org%2Fiel7%2F6493540%2F6495011%2F06495029.pdf%3Farnumber%3D6495029>

What is the SAT problem ?

$$F = (v_{11} \vee v_{12} \vee v_{13}) \wedge (v_{21} \vee v_{22} \vee v_{23}) \wedge \dots \wedge (v_{n1} \vee v_{n2} \vee v_{n3})$$

Clause (3-SAT)

- Finding an assignment for all the variables such that all clauses are satisfied and F is true
- NP-Complete

How do we solve it

Local search !

Sparrow local search solver

- Winner of 2011 SAT competition
- Part of UBCAST framework
- <https://github.com/dtompkins/ubcsat/tree/satcomp2011-sparrow>

Local Search for SAT

```
0: for try = 1 to MaxTries {  
1:     A = variable-initialization(F)  
2:     for Iteration = 1 to MaxFlips {  
3:         if A satisfies F then  
4:             return A  
5:         x = select-variable(A)  
6:         A = A with x flipped  
7:     }  
8: }  
9: return "No solution"
```

Local Search for SAT

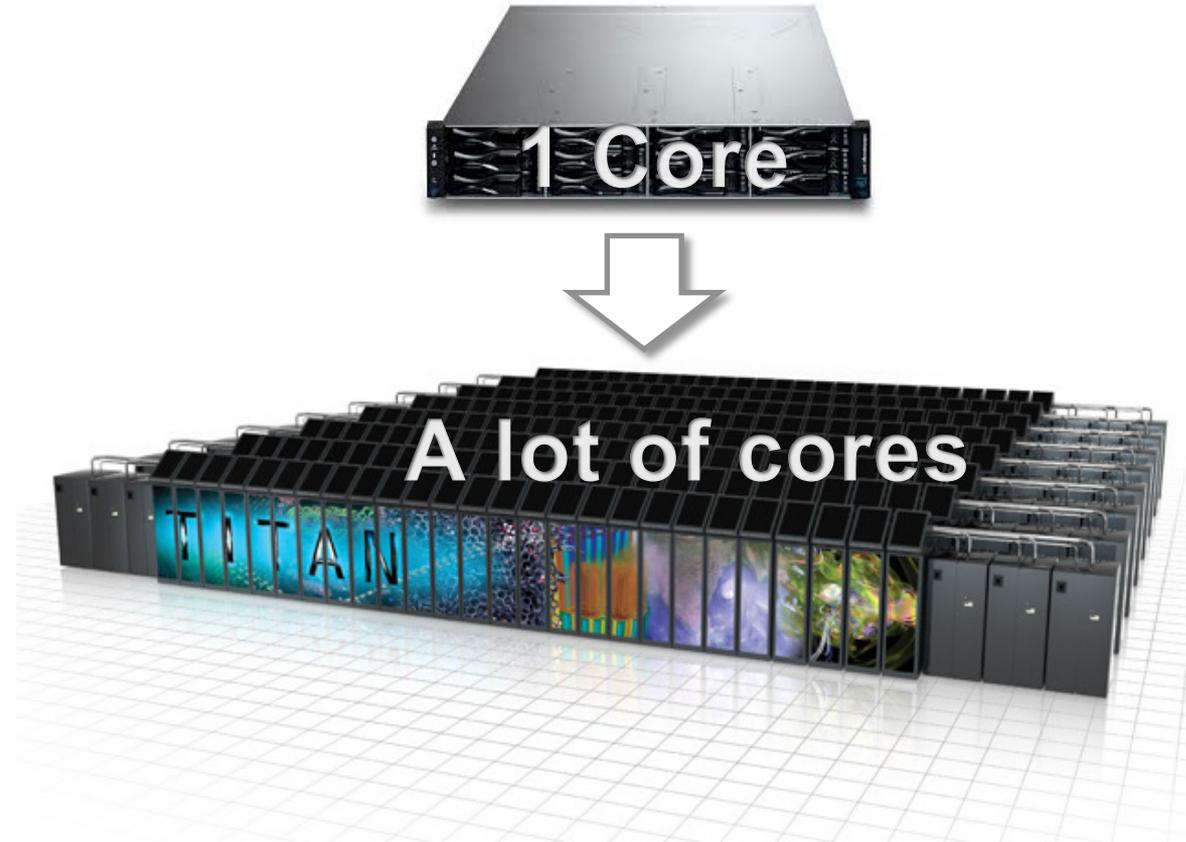
Starting point for the search

The “secret sauce”



```
1: for try = 1 to MaxTries {  
2:   A = variable-initialization(F)  
3:   for Iteration = 1 to MaxFlips {  
4:     if A satisfies F then  
5:       return A  
6:     x = select-variable(A)  
7:     A = A with x flipped  
8:   }  
9: return “No solution”
```

Parallel Local Search



Portfolio-based Parallel Local Search

Each process
uses unique
SEED



```
0: Init-Seed(Process_ID)
0: Init-Seed(Process_ID)
0: Init-Seed(Process_ID)
0: Init-Seed(Process_ID)
0: for try = 1 to MaxTries {
1:     A = variable-initialization(F)
2:     for Iteration = 1 to MaxFlips {
3:         if A satisfies F then
4:             eureka-return(A)
5:         x = select-variable(A)
6:         A = A with x flipped
7:     }
8: }
9: return "No solution"
```

Code Snippet

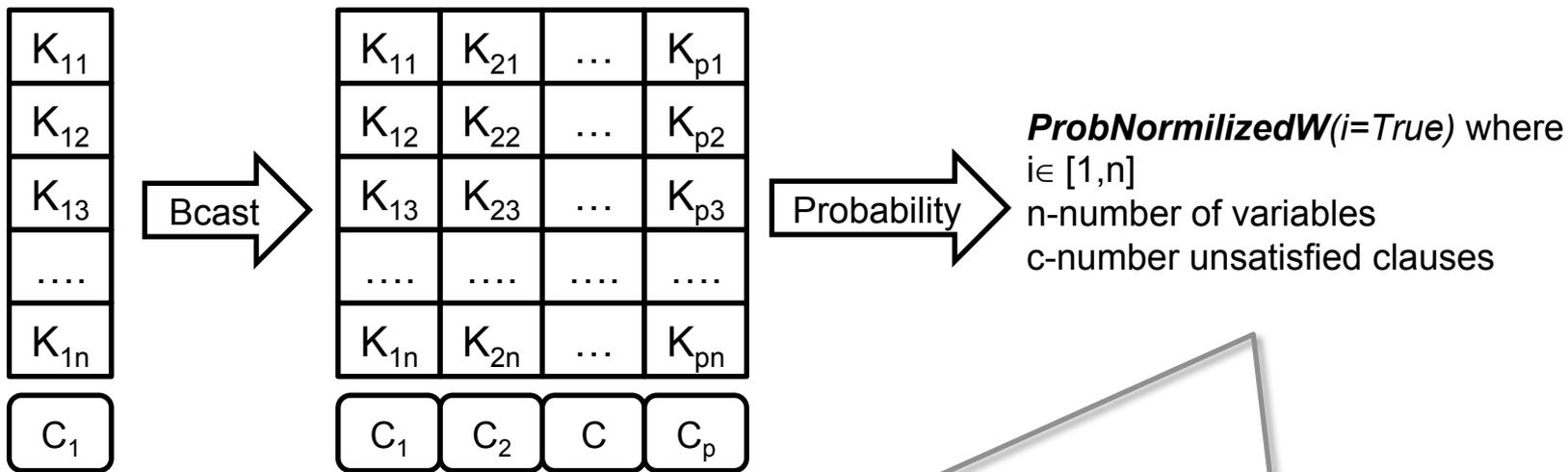
```
0: Init-Seed(Process_ID)
0: for try = 1 to MaxTries {
1:     A = variable-initialization(F)
2:     for Iteration = 1 to MaxFlips {
3:         if A satisfies F then
4:             eureka-return(A)
5:             x = select-variable(A)
6:             A = A with x flipped
7:         }
8:     }
9: return "No solution"
```

start_pe(0);
*seed = atoi(argv[2]) * (1+shmem_my_pe());*

/ OpenSHMEM 1.2 */*
shmem_global_exit(0);

/ OpenSHMEM 1.2 */*
shmem_finalize();

Portfolio-based Parallel Local Search Information Sharing



$$ProbNormalizedW(i = true) = \frac{\sum_{x \in [1, p]} K_{xi} * NormW_x}{\sum_{x \in [1, p]} NormW_x}$$

$$NormW_x = \frac{|C| - C_x}{|C|}$$

$x - PE, i - variable$

Information Sharing

```

0: Init-Seed(Process_ID)
0: for try = 1 to MaxTries {
1:     A = variable-initialize
2:     for Iteration = 1 to F
3:         if A satisfies
4:             return
5:         else
6:             if A satisfies
7:                 return
8:             }
9: return

```

$$ProbNormilizedW(i = true) = \frac{\sum_{x \in C} W_x}{\sum_{x \in C} W_x}$$

$$NormW_x = \frac{|C| - C_x}{|C|}$$

$x - PE, i - variable$

```

start_pe(0);
seed = atoi(argv[2]) * (1+shmем_my_pe());
/* Vector of values */
rem_aVarValue = shmемalloc(iNumVars * sizeof(BOOL) *
shmем_n_pes());
if (rem_aVarValue == NULL) {
    fprintf(stderr, "Failed to allocate memory for rem_aVarValue\n");
    shmем_global_exit(1);
}
memset(rem_aVarValue, 0, sizeof(BOOL) * shmем_n_pes());
/* Cost of the current solution */
rem_iNumFalse = shmемalloc(sizeof(UINT32) * shmем_n_pes());
if (rem_iNumFalse == NULL) {
    fprintf(stderr, "Failed to allocate memory for rem_iNumFalse\n");
    shmем_global_exit(1);
}
memset(rem_iNumFalse, 0, sizeof(UINT32) * shmем_n_pes());
/* Signal that data is ready */

```

```

int i;
for (i = 0; i < shmем_n_pes(); i++) {
    shmем_putmem(get_rem_avar(shmем_my_pe(), 0),
aVarValue, iNumVars*sizeof(BOOL), i);
    shmем_putmem(get_rem_inum(shmем_my_pe()),
&iNumFalse, sizeof(UINT32), i);
    /* Announce update */
    shmем_fence();
    shmем_longlong_inc(&rem_counter[shmем_my_pe()], i);
}

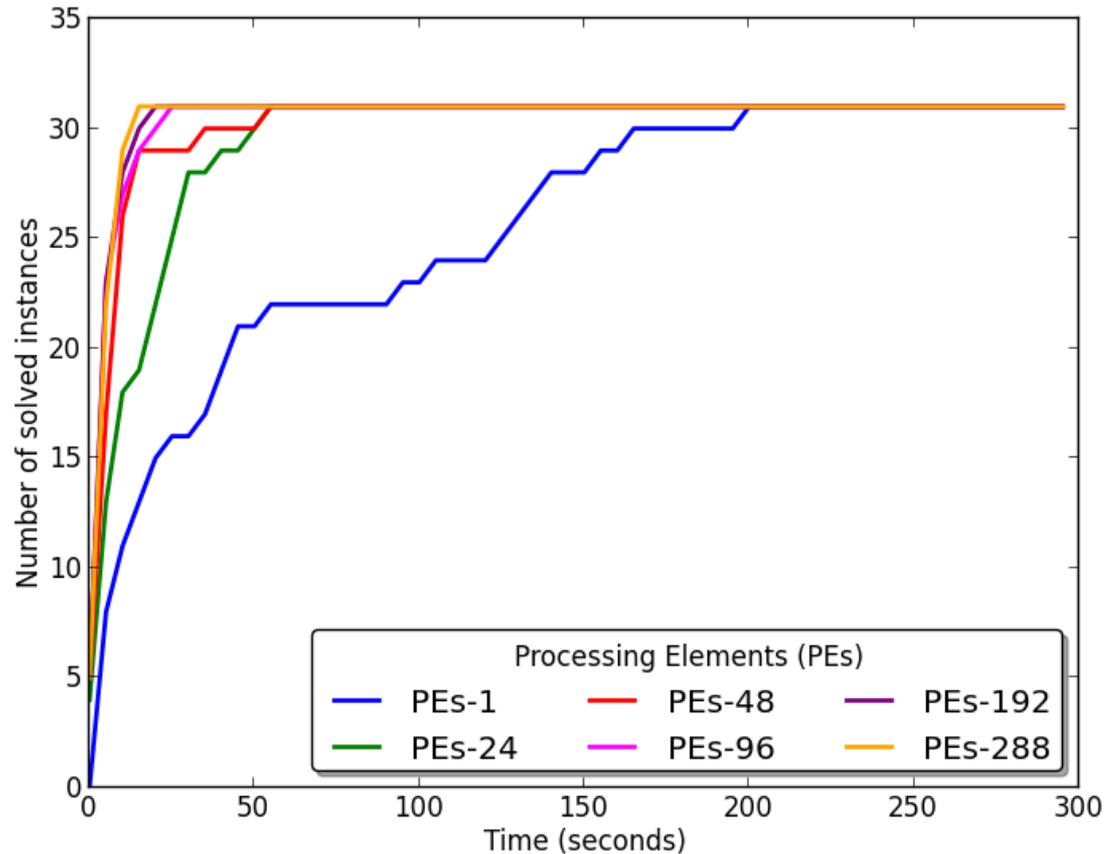
```

What Algorithm Performed the Best ?

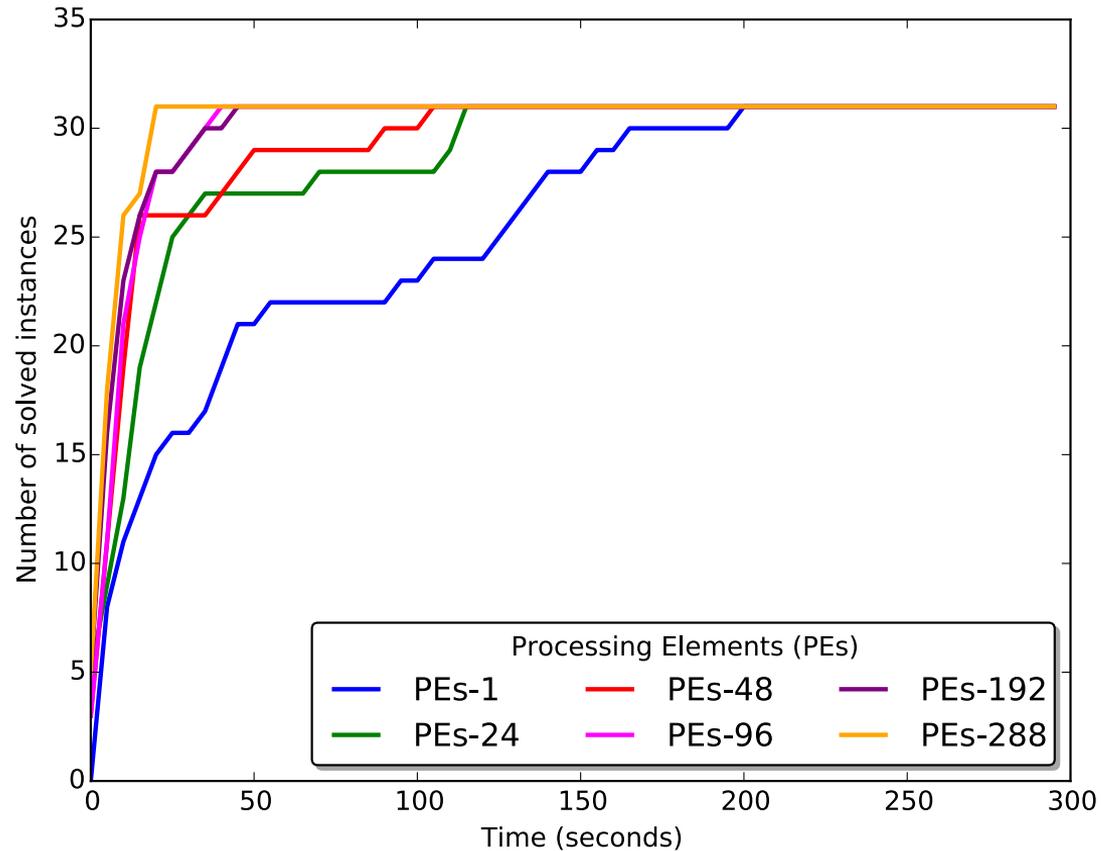
Test-bed

- SGI Altix
- 12 nodes each one with 24 cores (288 cores in total)
- Processing Element (PE) per core
- InfiniBand interconnect
- 50 instances from SAT2011 (random)
- 3-SAT (x20), 5-SAT(x20), 7-SAT(x10)
- 3 iterations for each instance / median reported

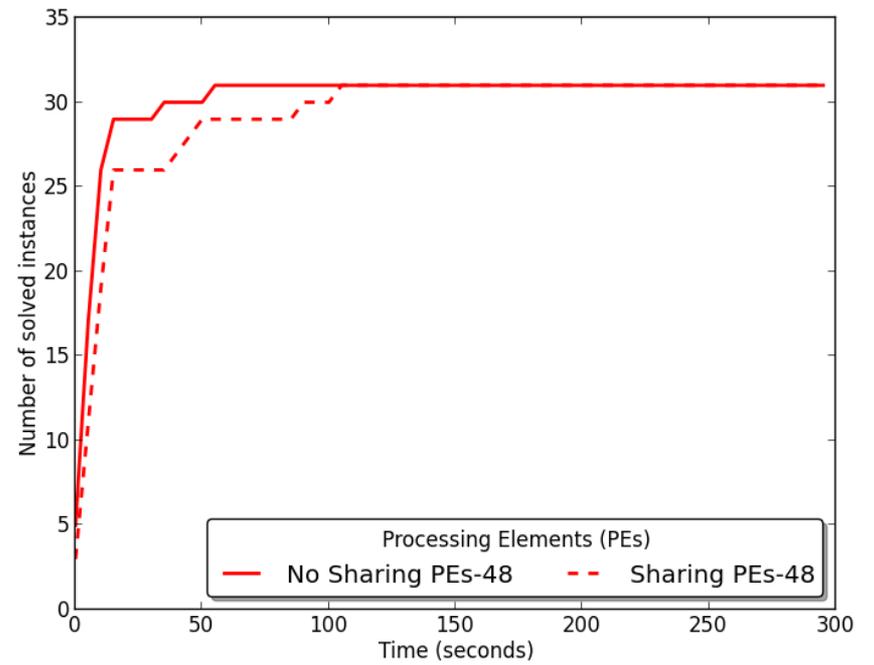
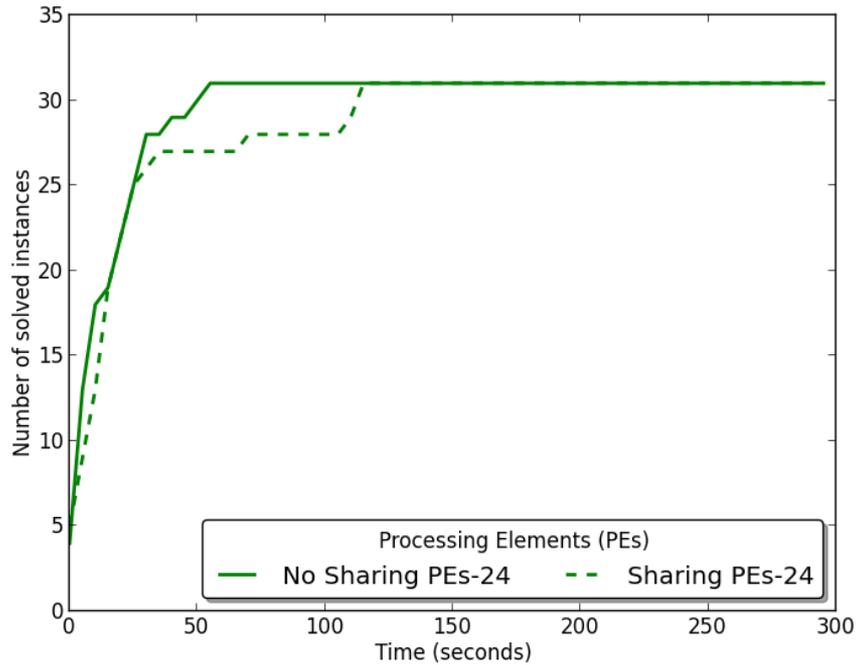
Performance – No Information Sharing



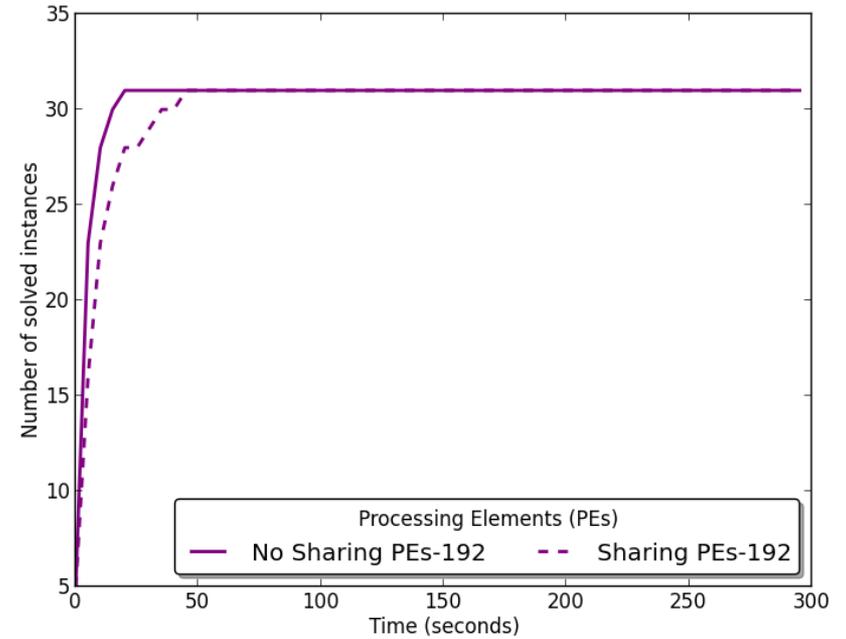
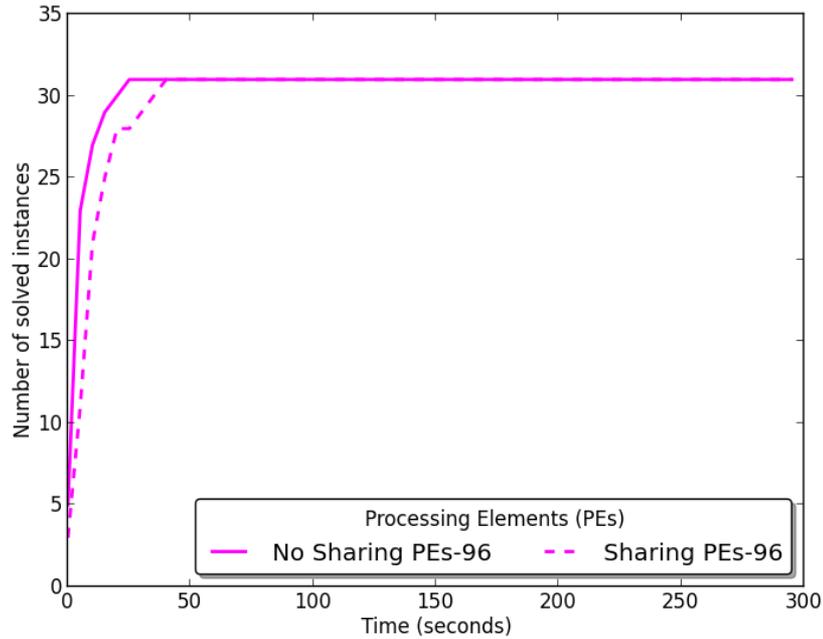
Performance – Information Sharing



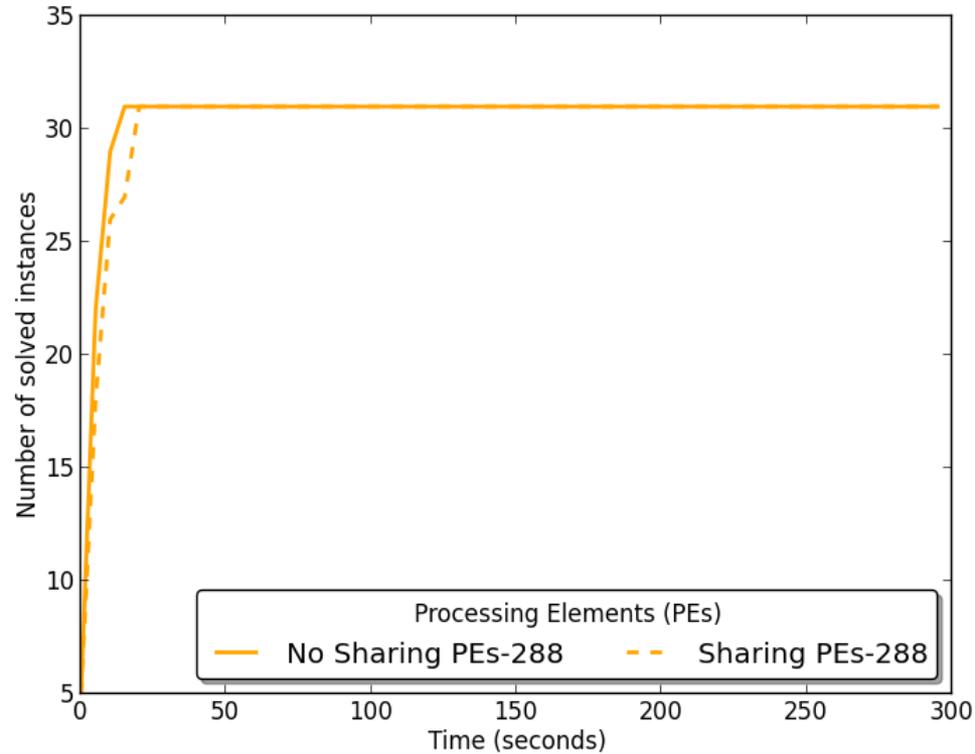
Sharing VS No-sharing



Sharing VS No-sharing



Sharing VS No-sharing



Thanks !

Questions ?

OpenSHMEM Serial to Parallel Code Conversion Distributed Hash Table (DHT)

Dounia Khaldi
University of Houston

The Orbit Calculation Problem

- Application benchmark:
 - Group theory
 - Calculation of the orbits of a group G acting on a set M
 - Graph traversal problem, where each graph vertex is a group element
- For each graph vertex, compute some of its properties
- Which other graph vertices is a vertex connected to?

Notion of Orbit

Input: $m_0 \in M$, Group $G = \{g_i, 1 \leq i \leq r\}$

Output: A list L containing the elements of m_0G (G -orbit of m_0)

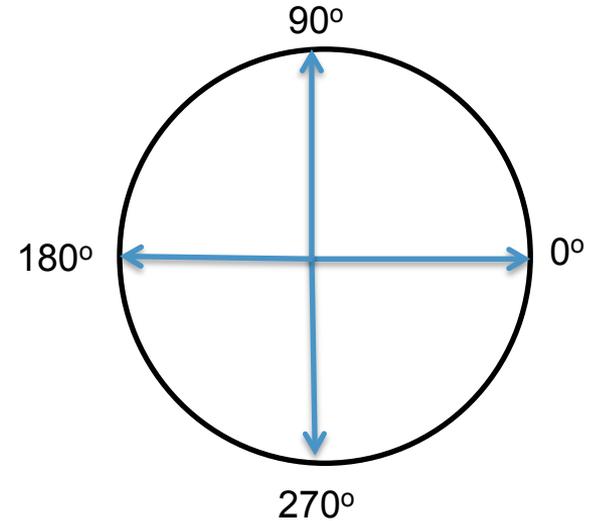
Example:

- M is a set of vectors
- G is a group of four 90° rotations

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

- Composition of rotations corresponds to matrix multiplication
- **Orbit:** mG

$$\begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$



$$G = \{R(0^\circ), R(90^\circ), R(180^\circ), R(270^\circ)\}$$

The Orbit Basic Algorithm

Input: $m_0 \in M$, Group $G = \{g_i, 1 \leq i \leq r\}$

Output: A list L containing the elements of m_0G (G -orbit of m_0)

```
L := [m0]
```

```
for i from 1 to r do
```

```
  x := m0gi // element of orbit of m0
```

```
  if x is not in L then
```

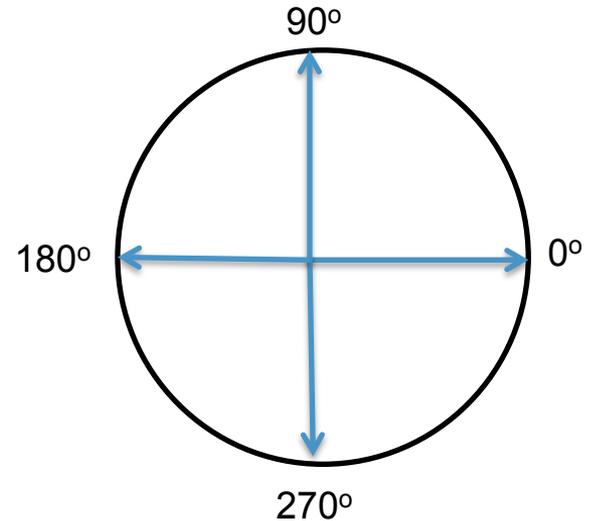
```
    append x to L
```

```
  end if
```

```
end for
```

```
return L
```

} **DHT**

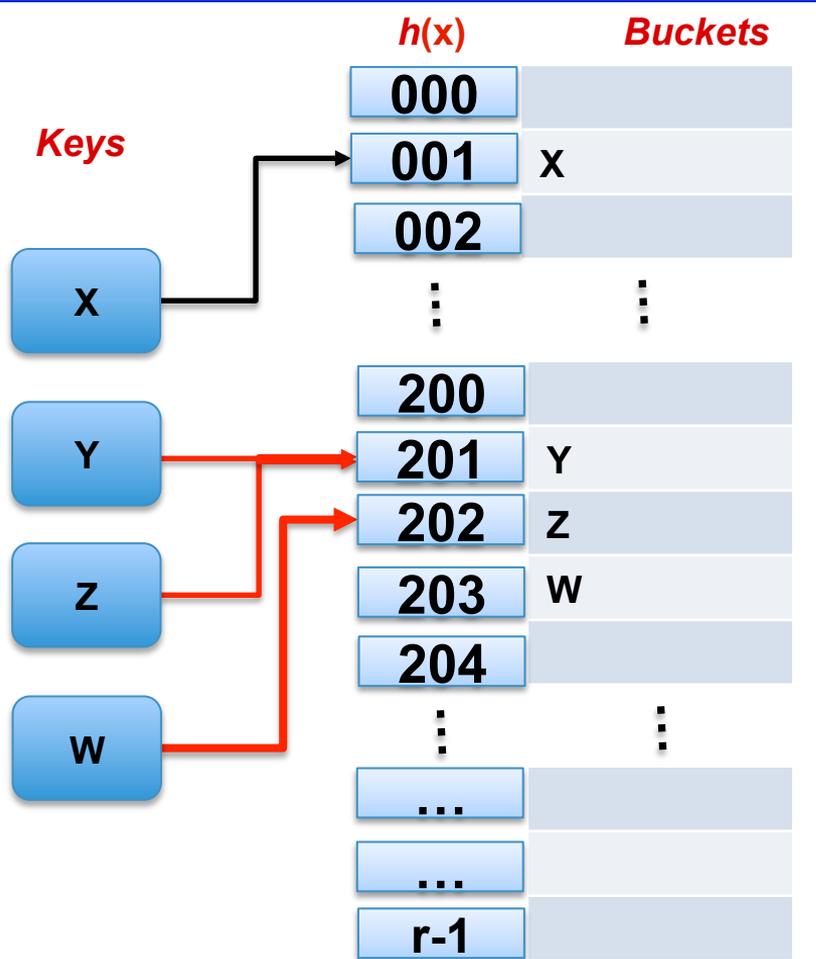


$G = \{R(0^\circ), R(90^\circ), R(180^\circ), R(270^\circ)\}$

Orbit Calculation: Serial Hash Table

- Linear lookup of points in lists (sequential comparison) expensive for large orbits
- Hash table to keep track of whether a vertex has been visited
- Lookups using hash tables almost independent of the orbit length
- Limited to certain size of groups by the amount of memory available in serial implementation
- Parallel (distributed) implementation to allow larger orbits

DHT: Open Addressing Strategy



Implementation

- **insert ()** puts new entry in the hash table if not present
- **lookup ()** searches for a key
- **delete ()** frees entry to remove from the hash table

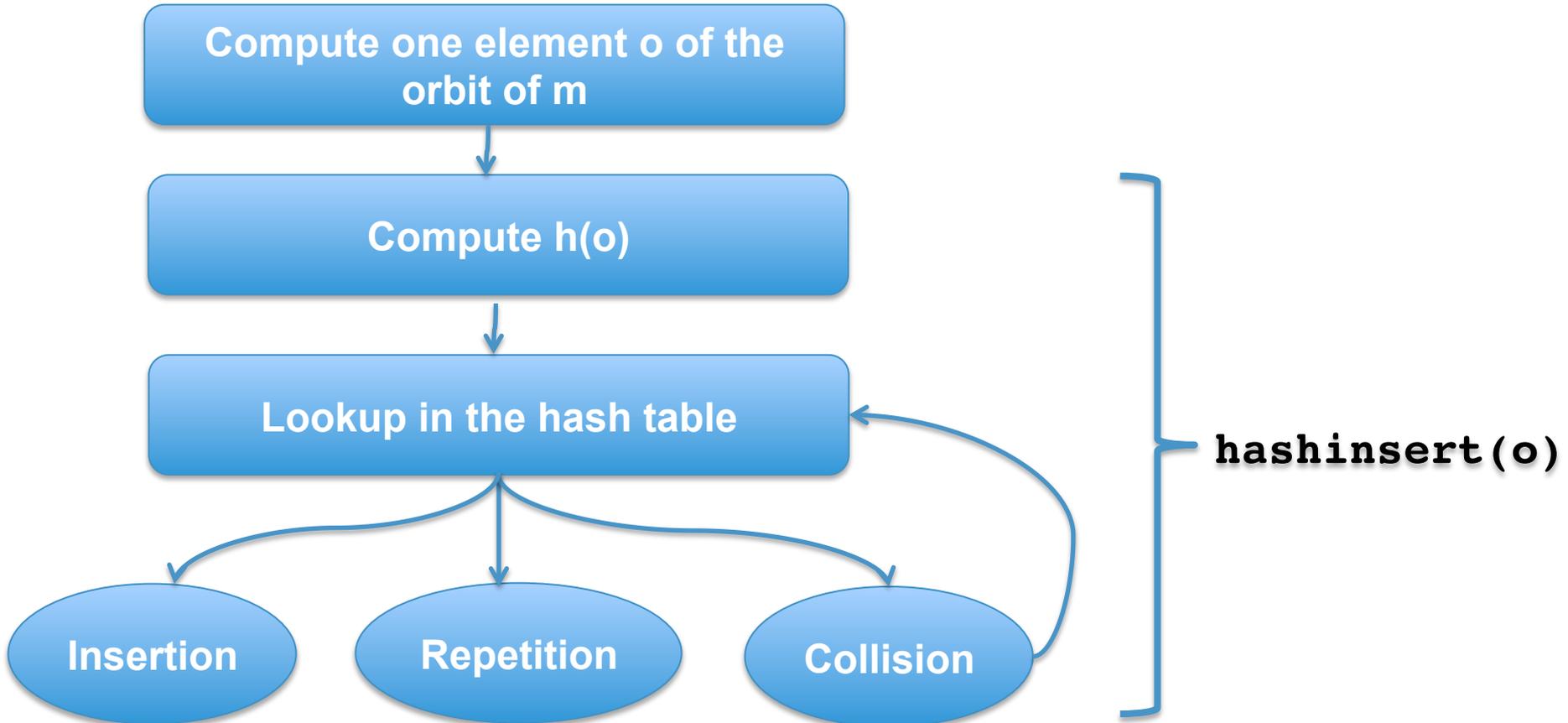
Advantages

- Lookup is fast
- Insertion is fast
- Unlike chaining, it cannot have more elements than table slots

Disadvantage

- Deletion should take into account collisions

DHT: Sequential Code



DHT: Data Structures

- `hashtab`: the memory where to store the orbit
- `hashcount`: number of repetitions
- `hashlen`: max size of the orbit (r)
- `collisions`: number of collisions
- `dest_pos`: the index of an element of the orbit in `hashtab`
- `local_val`: the value of an element of `hashtab`

DHT: Sequential Code (hashinsert(o))

- Size of G (r : number of vertices): $\text{hashlen} = r$;

```
dest_pos = h(o);
```

```
while (1) {
```

```
    local_val = hashtable[dest_pos];
```

```
    if (local_val == 0) {
```

```
        hashtable[dest_pos] = o;
```

```
        hashcount[dest_pos] = 1;
```

```
        return;
```

```
    } else if (local_val == o) {
```

```
        hashcount[dest_pos]++;
```

```
        return;
```

```
    } else {
```

```
        collisions++;
```

```
        dest_pos++;
```

```
        if (dest_pos == hashlen)
```

```
            dest_pos = 0;
```

```
    }
```

```
}
```



insert in the empty entry



**check to see if
it is not a collision**



it is a repetition



it is a collision

DHT: Sequential Code (hashinsert(o))

```
dest_pos = h(o);
while (1) {
    local_val = hashtable[dest_pos];
    if (local_val == 0) {
        hashtable[dest_pos] = o;
        hashcount[dest_pos] = 1;
        return;
    } else if (local_val == o) {
        hashcount[dest_pos]++;
        return;
    } else {
        collisions++;
        dest_pos++;
        if (dest_pos == hashlen)
            dest_pos = 0;
    }
}
```

RMA (get)

RMA (put)

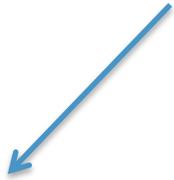
Exclusive accesses to hashtable and hashcount

Distributed Hash Table (DHT)

- The sender would know the identity of the receiver via hash, but not vice versa
- Larger hash tables created in parallel than can be done serially →
 much larger orbits
- Suitable for OpenSHMEM →
 requires RMA

DHT: OpenSHMEM Code Initialization

`hashlen = r`



```
void inithash()
```

```
{
```

```
    npes = shmem_n_pes();
```

```
    mype = shmem_my_pe();
```

```
    hashlen = r;
```

```
    localhashlen = hashlen/npes;
```

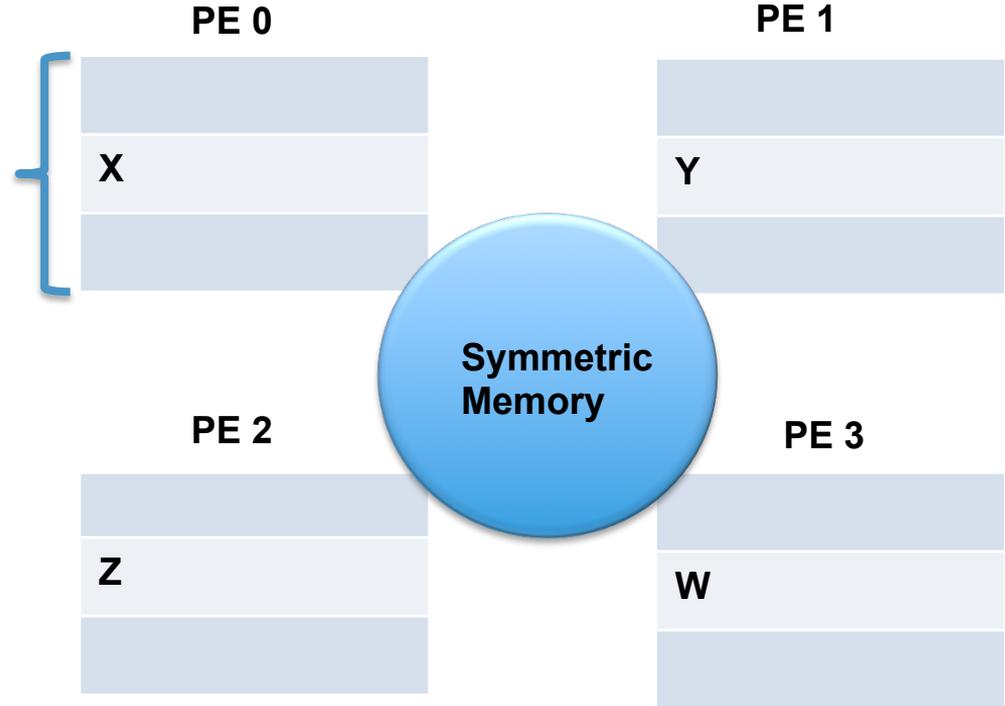
```
    hashtab = shmem_malloc( localhashlen * sizeof *hashtab );
```

```
    hashcount = shmem_malloc( localhashlen * sizeof *hashcount );
```

```
    pe_lock = shmem_malloc( npes * sizeof *pe_lock );
```

```
    memset( pe_lock, 0, npes * sizeof *pe_lock);
```

```
}
```



DHT: OpenSHMEM Code

```
#include <shmem.h>
//declaration of hashtab, hashcount,...
void orbit(m0,G)
{
    shmem_init();
    inithash();
    shmem_barrier_all();
    for (i = mype; i < hashlen; i+=npes) {
        hashinsert(apply(m0, g[i]));
    }
    shmem_barrier_all();
    finhash();
    shmem_finalize();
    return;
}
```

 **Allocate symmetric variables**

 **Free symmetric variables**

DHT: OpenSHMEM Hash Finish

```
void finhash()  
{  
    shfree(hashtab);  
    shfree(hashcount);  
    shfree(pe_lock);  
}
```

DHT: OpenSHMEM Code Using Locks

`hashinsert(o)`

```
hash = h(o);
while (1) {
    dest_pe = ceil(hash / localhashlen);
    dest_pos = hash - (dest_pe)*localhashlen;
    /* lock the data */
    shmem_set_lock(&pe_lock[dest_pe]);
    shmem_int_get(&local_val, &hashtab[dest_pos], 1, dest_pe);
```

DHT: OpenSHMEM Code Using Locks

```
/* check to see if o already exists */
if (local_val == 0) {
    /* insert the entry */
    int one = 1;
    shmem_int_put(&hashtab[dest_pos], &o, 1, dest_pe);
    shmem_int_put(&hashcount[dest_pos], &one, 1, dest_pe);
    /* unlock before return */
    shmem_clear_lock(&pe_lock[dest_pe]);
    return;
}
else... // repetition or collision
```

DHT: OpenSHMEM Code Using Locks

```
/* check to see if it is not a collision */
else if (local_val == 0) {
    /* it is a repetition */
    shmem_int_inc(&hashcount[dest_pos], dest_pe);
    shmem_clear_lock(&pe_lock[dest_pe]);
    return;
} else { /* it is a collision */
    collisions++;
    hash++;
    if (hash == hashlen) {
        hash = 0;
    }
    shmem_clear_lock(&pe_lock[dest_pe]);
}
}
```

DHT: OpenSHMEM Code Using Locks

shmem_int_cswap?

```
hash = h(o);
while (1) {
    dest_pe = ceil(hash / localhashlen);
    dest_pos = hash - (dest_pe)*localhashlen;
shmem_set_lock(&pe_lock[dest_pe]);
shmem_int_get(&local_val, &hashtab[dest_pos], 1, dest_pe);
    if (local_val == 0) {
        int one = 1;
shmem_int_put(&hashtab[dest_pos], &o, 1, dest_pe);
        shmem_int_put(&hashcount[dest_pos], &one, 1, dest_pe);
        /* unlock before return */
shmem_clear_lock(&pe_lock[dest_pe]);
        return;
    }
    else...    //repetition or collision;
```

DHT: OpenSHMEM Code Using Locks

```
/* check to see if it is a collision */
else if (local_val == 0) {
    /* its a repetition */
    shmem_int_inc(&hashcount[dest_pos], dest_pe);
    shmem_clear_lock( &pe_lock[dest_pe] );
    return;
} else { /* its a collision */
    collisions++;
    hash++;
    if (hash == hashlen) {
        hash = 0;
    }
    shmem_clear_lock( &pe_lock[dest_pe] );
}
}
```

DHT: OpenSHMEM Code Using AMO

```
hash = h(o);
while (1) {
    dest_pe = ceil(hash / localhashlen);
    dest_pos = hash - (dest_pe)*localhashlen;
    local_val = shmem_int_cswap(&hashtab[dest_pos],0,o,dest_pe);
    if (local_val == 0 || local_val == o) {
        /* update successful, so increment count and return */
        shmem_int_inc(&hashcount[dest_pos], dest_pe);
        return;
    }
    else
        /* it's a collision */

```

DHT: OpenSHMEM Code Using AMO

```
else { /* its a collision */
    collisions++;
    hash++;
    if (hash == hashlen) {
        hash = 0;
    }
}
}
```

DHT: Performance on Stampede using MVAPICH2-X

Interconnect:

InfiniBand Mellanox Switches/HCAs

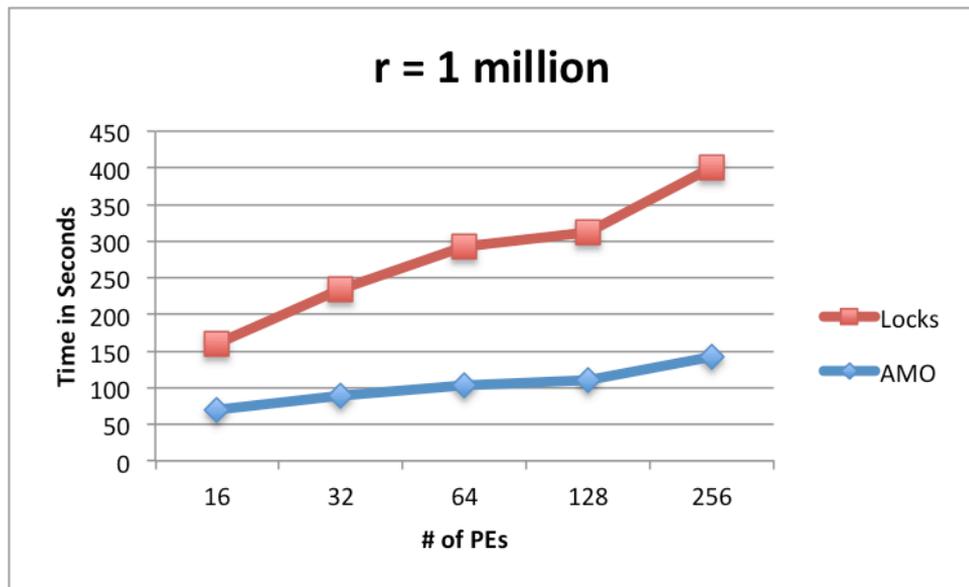
Cores/Node: 16

- We used 16 PEs/nodes

Version: mvapich2-x/2.0b

ICC 13.1.0

CFLAGS= -O2



DHT: Conclusion

- DHT: look up and store large orbits
- DHT: illustrative example of using OpenSHMEM (RMA, locks, atomics)
- Easy transition from sequential to parallel
- Use atomics if implementation is adapted

OpenSHMEM Implementation Components and Characteristics

Manjunath Gorentla Venkata
ORNL

OpenSHMEM Components and Characteristics

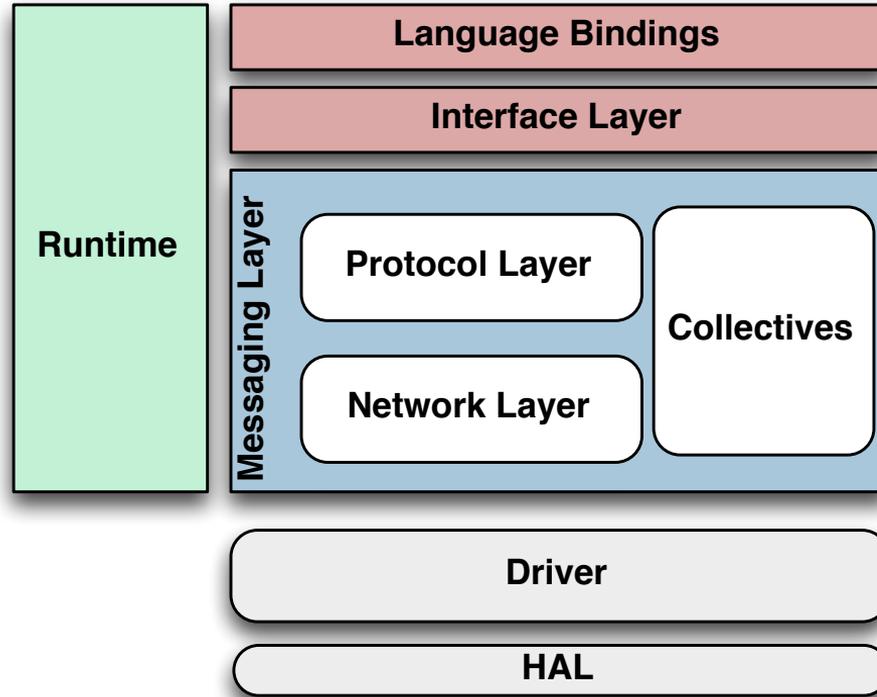
Goal:

Overview of components and its characteristics in a typical OpenSHMEM implementation

Expert level:

Introductory

Components in a Typical OpenSHMEM Implementation



Runtime Layer

Resides on the head node from which processes are launched, and typically a daemon resides in each node of the job

Functions

- Launches the job, leveraging job launchers such as rsh, ssh, slurm, pbs
- Provides out-of-band communication
- Fault detection and recovery
- Provides flexible process binding functionality

Examples

Launchers

- ALPS, SSH, Hydra

Runtime Implementations

- STCI - Runtime that supports fault-tolerance
- ORTE – Runtime for Open MPI
- PMI – Runtime for MPICH based implementations
- SLURM PMI, BG/L PMI, Simple PMI

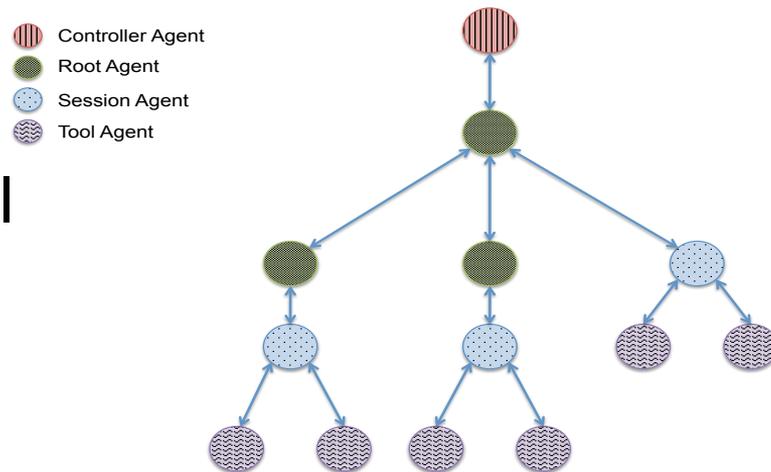
Interfaces for abstracting various runtime layers

- Librte – Library interface for runtimes
- Process Manager Interface (PMI)

Case Study: STCI

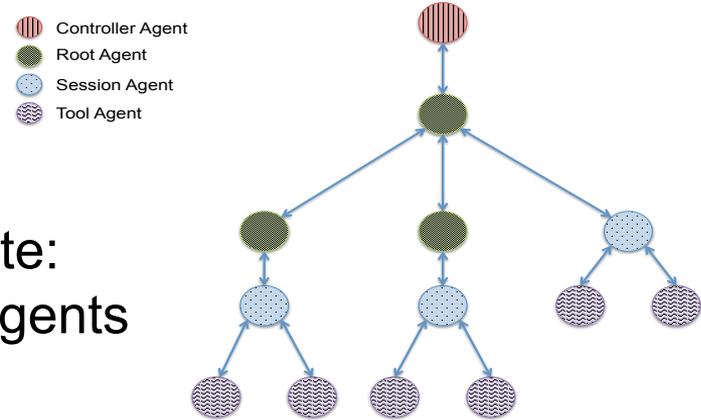
Components

- Agents
 - Controller, Root, Session, Tool
- Topology
 - Connects various agent components
 - Currently supports tree, meshes, BMGs



Case Study: STCI

- Communication Substrate
 - Bootstrap communication substrate :
 - Self-bootstrapping
 - Reliable and ordered
 - Active message communication substrate:
 - Provides communication between agents after bootstrapping
- Fault tolerance : Enables communication even in the event of failed agents
 - Fault detection
 - Fault tolerant communication



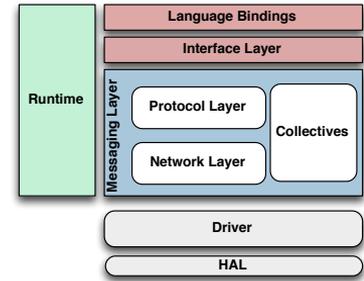
Messaging Layer

Protocol Layer

- Implements semantics of the programming model
- Provides protocols to support the programming model semantics and achieve performance
- Provides message fragmentation and coalescing abilities
- RDMA Protocols, Active Messages, Atomics

Network layer

- Transfers data between processing elements
- Typically hardware and network dependent, and this component requires to re-implementing for porting the message layer



Example

Programming model specific

- Mellanox SHMEM
- Open MPI /MPICH
- OpenSHMEM reference implementation

Independent of Programming model

- UCX/UCS
- PAMI
- MXM
- Libfabric
- GASNet

Case Study: UCX

Yossi will provide a detailed talk on UCX

What Collective Operations ?

- Collective operations are global communication and synchronization operations in a parallel job
- Important component of a parallel system software stack
- Simulations are sensitive to collectives performance characteristics
- Simulations spend significant amount of time in collectives

Examples

Part of messaging layer

- OpenMPI – Tuned, Cheetah
- PAMI
- OpenSHMEM (reference implementation)

Standalone Libraries

- LibNBC
- HCOL (derived from Cheetah)
- FCA



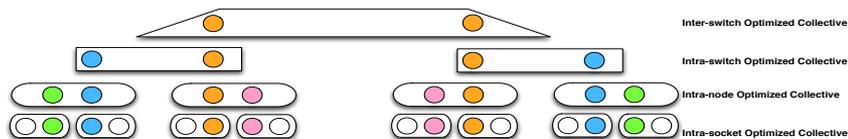
Case Study : Cheetah

Objectives

- Develop a high-performing and highly scalable collective operations library for multicore systems
- Develop collective offload mechanism for InfiniBand HCA
- Designed to support blocking and nonblocking semantics, and achieve high scalability and performance on modern multicore systems

Our Approach: Hierarchical Collectives

- A collective operation is a combination of multiple (layered) collective primitives.
- Group processes into multiple hierarchies to leverage architecture capabilities
- Build a collective by combining these basic collective primitives
- Progress independent collective primitives concurrently



Cheetah Collective



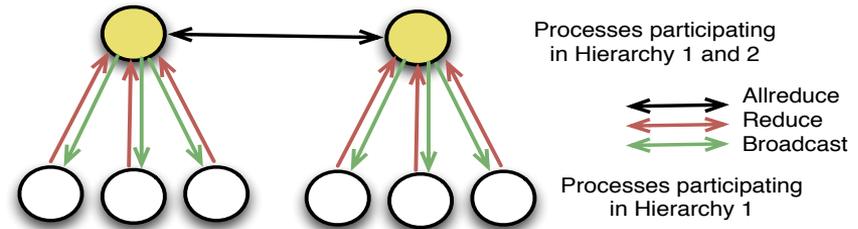
Regular Collective

Definitions: Reduction Operations

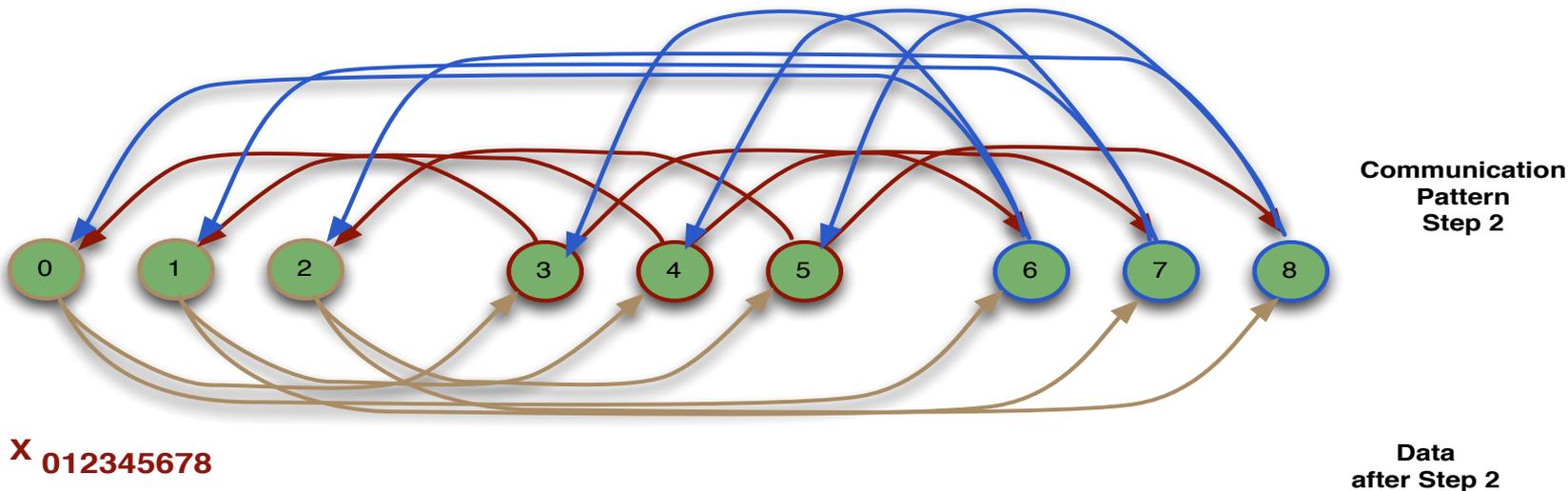
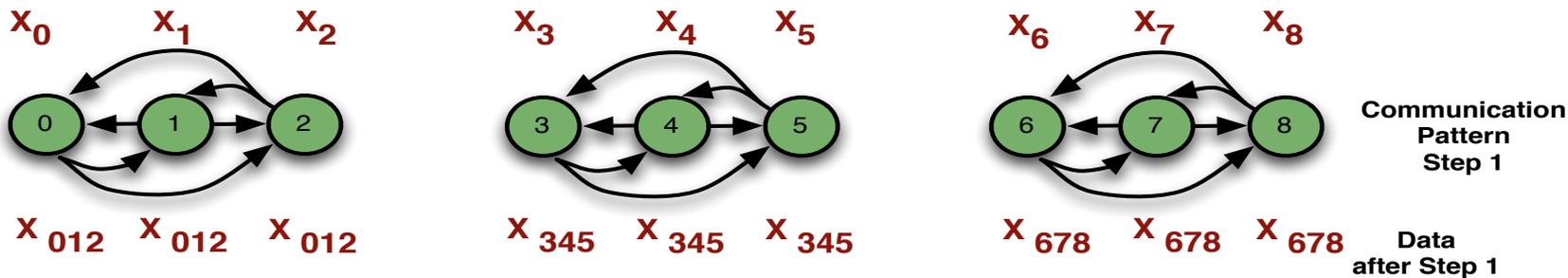
- Allreduce Operation: Combines the data from all participants with an operation, and distributes the results of the operation to all participants
- Reduce Operation: Combines the data from all participants with an operation, and the result is available only at the root

Hierarchical Allreduce Collective Operation

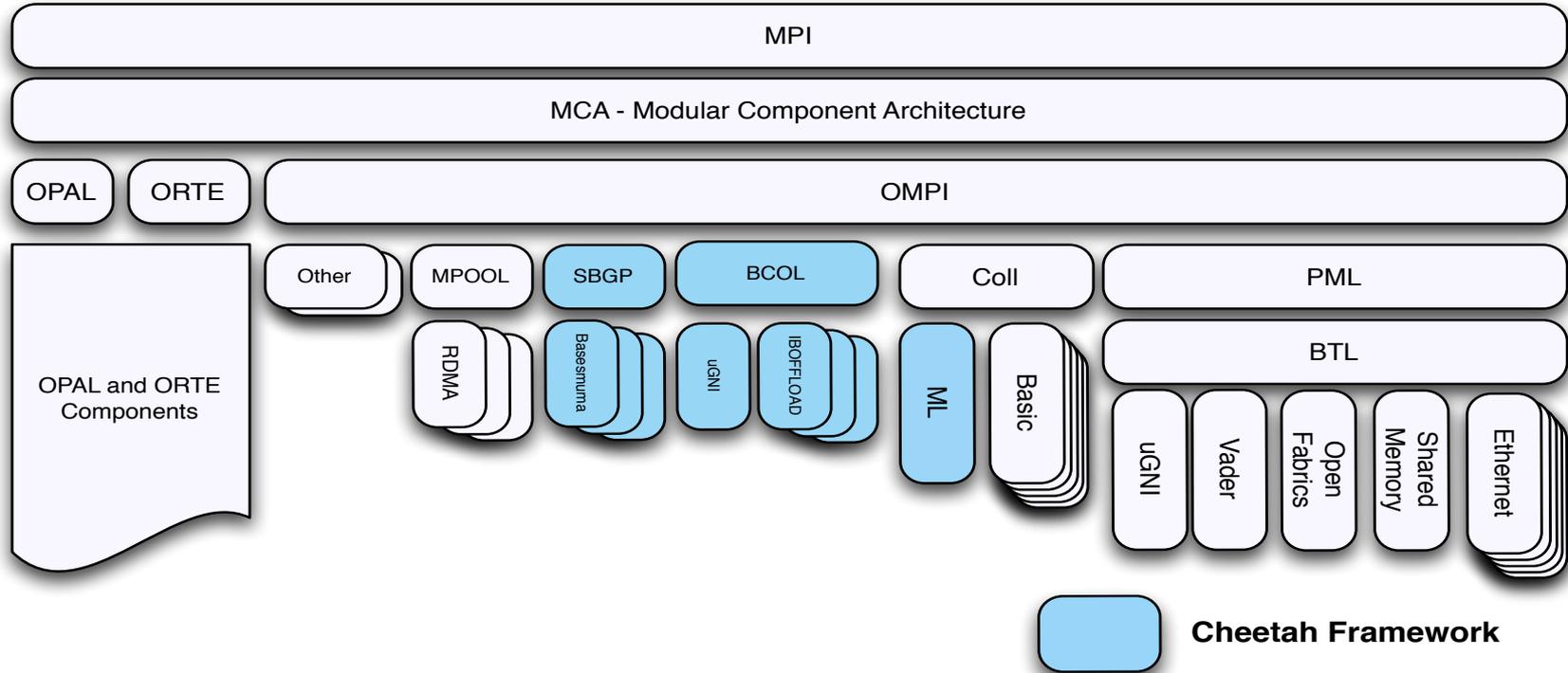
- A hierarchical allreduce is implemented as a combination of the reduce, allreduce, and broadcast primitives
- n level Allreduce is a combination of three primitives
- Reduce (first n-1 levels), Allreduce(nth level), Broadcast (first n-1 levels)
- Example: Interaction of the collective primitives in a 8-process allreduce collective operation



Recursive K'ing Algorithm for Implementing Allreduce Primitive



Cheetah : A Framework for implementing hierarchical collectives



Driver

Provides low level messaging functionality

- For RDMA networks it provides – RDMA Read, Write, Atomic interfaces
- Provide thin layer of active messages on RDMA network

The functionality is accessible through well-defined interface

- The interfaces are well-defined, but might change more rapidly

The lowest interface to the network interface

- It is not typically portable across the same hardware or different hardware

Examples

Verbs

- Driver for InfiniBand

uGNI

- Driver for Cray's Gemini and Aries NICs
- Primarily used for implementing MPI

DMAPP

- Driver for Cray's Gemini and Aries NICs
- Primarily used for implementing PGAS models

Case Study : Verbs

What is Verbs ?

- A low level abstraction of the network device, and is close to bare metal for many HCAs
- Provides RDMA functionality for the upper-layer protocols

Why use Verbs ?

- Low-level interface - for portability, performance and scalability
- Provides kernel bypass

Case Study: Verbs (Continued)

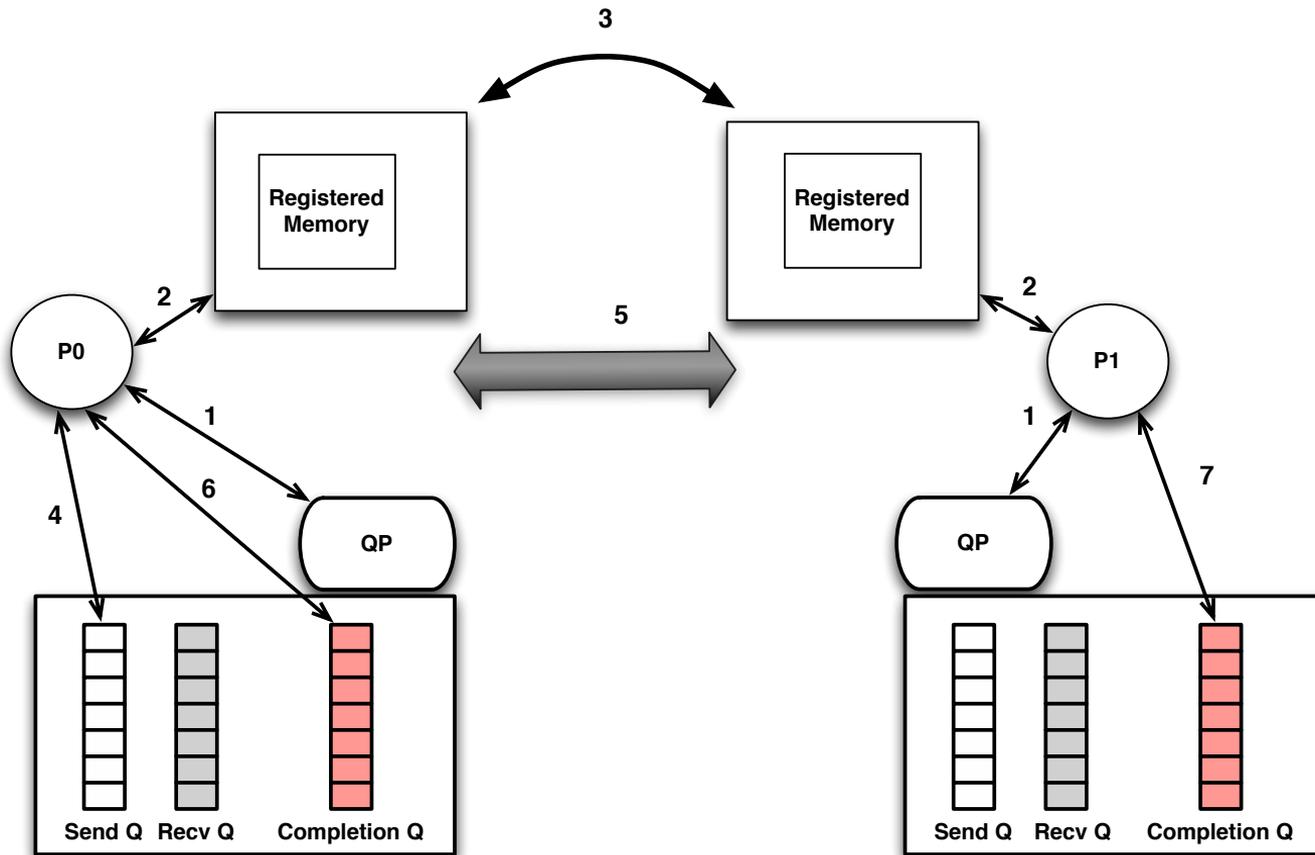
Constructs

- Objects : QPs, SQ, RQ, CQ, Memory Region
- Functions:

Control Functions : Create, Destroy, Modify, Query, Work with events

Data Functions : Post Send, Recv, Poll CQ, Request for completion event

Example of Message Transfer using Verbs on InfiniBand

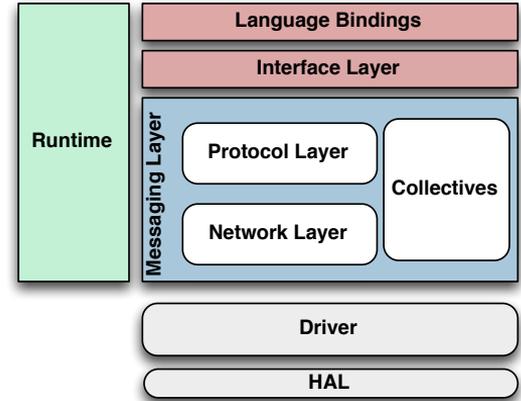


References

- <https://zcopy.wordpress.com/2010/10/08/quick-concepts-part-1---introduction-to-rdma/>
- <http://www.digitalvampire.org/rdma-tutorial-2007/slides.pdf>
- http://www.csm.ornl.gov/workshops/openshmem2013/documents/presentations_and_tutorials/Tutorials/Verbs%20programming%20tutorial-final.pdf

Stack Trace: shmем_put call (First Packet)

```
#0 0x00007f2694bcc160 in ibv_create_qp ()
#1 0x00007f2694e0040c in qp_create_one ()
#2 0x00007f2694e001dd in qp_create_all ()
#3 0x00007f2694dff7af in oob_module_start_connect ()
#4 0x00007f2694df43fa in check_endpoint_state ()
#5 0x00007f2694df41ef in mca_tl_openib_put_short_nb ()
#6 0x0000000000403352 in uccs_put_contiguous_short_nb ()
#7 0x0000000000403169 in uccs_put ()
#8 0x0000000000403049 in __shmем_comms_put ()
#9 0x00000000004034a2 in shmем_int_put ()
#10 0x0000000000403f7c in shmем_int_p ()
#11 0x0000000000402054 in main ()
```



Stack Trace: shmем_put call (Subsequent Packets)

#0 ibv_post_send ()

#1 0x00007fe21fe3d32e in mca_tl_openib_put_short_nb ()

#2 0x0000000000403366 in uccs_put_contiguous_short_nb ()

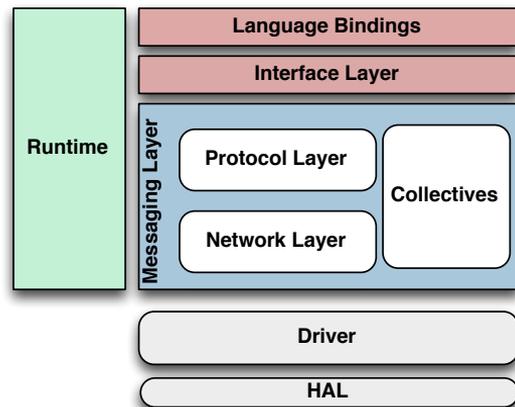
#3 0x000000000040317d in uccs_put ()

#4 0x000000000040305d in __shmем_comms_put ()

#5 0x00000000004034b6 in shmем_int_put ()

#6 0x0000000000403f90 in shmем_int_p ()

#7 0x0000000000402068 in main ()



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Latest in OpenSHMEM: Specification, API, and Programming

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