A fourth order accurate finite difference scheme for the elastic wave equation in second order formulation¹

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Computational seismology

 $\rho \mathbf{u}_{tt} = div\sigma + \mathbf{f}$

- $\mathbf{u} = \mathbf{u}(x, y, z, t)$ displacement vector ($\mathbf{u} = (u \ v \ w)$).
- $\mathbf{f} = \mathbf{f}(x, y, z, t)$ forcing = earthquake model
- stress tensor:

$$\sigma = \begin{pmatrix} (2\mu + \lambda)u_x & \mu(u_y + v_x) & \mu(u_z + w_x) \\ \mu(u_y + v_x) & (2\mu + \lambda)v_y & \mu(v_z + w_y) \\ \mu(u_z + w_x) & \mu(v_z + w_y) & (2\mu + \lambda)w_z \end{pmatrix}$$

▶ $\rho = \rho(x, y, z), \ \mu = \mu(x, y, z), \ \lambda = \lambda(x, y, z) \text{ mtrl. prop.}$





Domain and wave types

Computational domain



- Traction free boundary condition at surface.
- Pressure wave with speed $c_p = \sqrt{(2\mu + \lambda)/\rho}$.
- Shear wave with speed $c_s = \sqrt{\mu/\rho}$.
- Wave speed ratio $c_p/c_s > \sqrt{2}$.
- Rayleigh waves on surface, slower than P- and S-waves.

Topography handled by curvilinear grid



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Grid refinement for depth varying wave speeds.

Resolution requirements

$$h = \frac{\min c_s}{Pf}$$

- Grid spacing h
- Points per shortest wavelength P
- Highest frequency f
- Material shear wave speed c_s

Typical values: f = 10 Hz, $c_s = 300$ m/s, P = 15 (second order), P = 7 (fourth order), gives

$$h = 2m$$
 (2nd order) $h = 4.29m$ (4th order)

Domain size 200 km \rightarrow 100,000 pts/dimension (2nd) 46,620 (4th)

Objective

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This work (new): 4th order accurate energy conserving method.

Previous work: 2nd order accurate energy conserving method. Extensions to

- Curvilinear grids
- Far field boundaries
- Mesh refinement
- Viscoelastic model

Energy conserving methods for the elastic wave equation

 E^n discrete energy at t_n , integral over space, conserved when $\mathbf{f} = \mathbf{0}$

$$E^n = E^{n-1} = \ldots = E^0.$$

Compatibility with norm, $c_1||u^n||_h \leq E^n \leq c_2||u^n||_h$ gives stability,

$$||u^n||_h \leq E^n/c_1 = \ldots = E^0/c_1 \leq c_2/c_1||u^0||_h$$

- Stability for inhomogeneous material, real b.c., any c_p/c_s .
- Stable for long time integration
- Dissipation free
- Robust code, no numerical parameters to tune, but must be careful to not introduce unresolved frequencies

Energy estimate gives long time stability



Standard stability gives convergence on 0 < t < T with T fixed.

Example: Wave equation with mixed derivative term

$$u_{tt} = (2au_x + au_y)_x + (au_x + 2au_y)_y, \quad (x, y) \in [0, 1]^2, \ t > 0$$

a = a(x, y) > 0 variable coefficient. Boundary conditions:

$$u = 0 \qquad \text{at } x = 0$$

$$2u_x + u_y = 0 \qquad \text{at } x = 1$$

$$u(x, y, t) = u(x, y + 1, t) \text{ (periodic in } y)$$

Energy estimate

$$\frac{1}{2}\frac{d}{dt}\left(||u_t||^2 + (u_x, au_x) + (u_x + u_y, a(u_x + u_y)) + (u_y, au_y)\right) = 0$$

(Note: Non-negative terms give L^2 estimate) Derived by partial integration:

$$\frac{1}{2} \frac{d}{dt} ||u_t||^2 = (u_t, u_{tt}) = \dots = \\ -\frac{1}{2} \frac{d}{dt} ((u_x, 2au_x) + (u_x, au_y) + (u_y, au_x) + (u_y, 2au_y)) + B.T$$

Energy terms: $(u_x, au_x) + (u_x + u_y, a(u_x + u_y)) + (u_y, au_y)$
 $B.T. = u_t a(2u_x + u_y)|_{x=1} - u_t a(2u_x + u_y)|_{x=0}$ zero by b.c.

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Discretization

Cartesian grid with constant spacing *h*. Centered finite difference operators

$$\partial u(x_i)/\partial x \rightarrow D_0 u_i, \quad i=1,\ldots,N$$

satisfying summation-by-parts

$$(u, D_0v)_h = -(D_0u, v)_h + u_Nv_N - u_1v_1$$

in a discrete, weighted, scalar product $(u, v)_h$. Further notation:

$$D_+u_i = (u_{i+1} - u_i)/h,$$
 $D_-u_i = (u_i - u_{i-1})/h.$

In two dimensions: $D_0^{(x)}u_{i,j}$ and $D_0^{(y)}u_{i,j}$.

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Discretization

 $(au_y)_x \approx D_0^{(x)}(aD_0^{(y)}u)$ and $(au_x)_x \approx D_0^{(x)}(aD_0^{(x)}u)$ same energy estimate as for PDE possible, but

- Energy not positive definite, norm estimate not possible.
- Boundary condition $2u_x + u_y = 0$ implicit.

Second order method $(au_x)_x \approx D_+(a_{j-1/2}D_-u_j)$, where Energy estimate based on

$$D_{+}(a_{j-1/2}D_{-}u_{j}) = D_{0}(a_{j}D_{0}u_{j}) - \frac{h^{2}}{4}D_{+}D_{-}(a_{j}D_{+}D_{-}u_{j}),$$

Square completion with *x*-*y* terms Keeps energy pos. def.

Use of ghost points, gives explicit discrete b.c. with no boundary modification of D_+D_- .

Fourth order accurate operator

$$(au_x)_x \approx G(a, u)_j = D_0(a_j D_0 u_j) + \frac{h^4}{18} D_+ D_- D_+(a_{j-1/2} D_- D_+ D_- u_j)$$

 $- \frac{h^6}{144} (D_+ D_-)^2 (a_j (D_+ D_-)^2 u_j) + \text{boundary modifications}$

- G is five point wide operator away from the boundary.
- ▶ *D*⁰ SBP operator of order 4/2, needed for *xy*-derivatives.
- G also order 4/2. Boundary modified at $j = 1, \ldots, 6$.
- ▶ B.T.=0 in SBP is 4th order accurate b.c. \rightarrow 4th order error.
- ▶ Boundary modification of (D₊D₋)³ gives first order errors that can be made to cancel first order errors of D₀(aD₀u).
- Can expand G(a, u)_j = ∑⁸_{m=1}∑⁸_{k=1}β_{j,k,m}a_ku_m, j = 1,...,6. Coefficient tensor β with 129 non-zero elements out of 384.

G uses ghost points, D₀ does not.

4th order P-C time discretization gives energy conservation

Can prove time discrete energy conservation:

$$E^{n+1/2} = E^{n-1/2}.$$

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Method stable (energy positive) for CFL < 1.3. No stiffness for high order.

Numerical examples

Elastic wave equation, 2D

$$\rho u_{tt} = ((2\mu + \lambda)u_x)_x + (\lambda v_y)_x + (\mu v_x)_y + (\mu u_y)_y \\ \rho v_{tt} = (\mu v_x)_x + (\mu u_y)_x + (\lambda u_x)_y + ((2\mu + \lambda)v_y)_y$$

 $0 < x < L_x$, $0 < y < L_y$, t > 0. Initial data: u(x, y, 0) and $u_t(x, y, 0)$ given. Boundary data: y-periodic, with Dirichlet b.c. on $x = L_x$ and

$$(2\mu + \lambda)u_x + \lambda v_y = 0 \qquad x = 0$$
$$\mu(v_x + u_y) = 0 \qquad x = 0$$

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Energy test with random material

$$\rho(x,y) = 4 + \theta$$
 $\mu(x,y) = 2 + \theta$ $\lambda(x,y) = 2(r^2 - 2) + \theta$

Random variable $\theta \in [0, 1]$. Approximate wave speed ratio $r = c_p/c_s$. Initial data also random numbers.



Energy change per time step. Total > 220,000 steps. c_p/c_s arbitrarily large.

Rayleigh waves

Surface waves at x = 0, solutions \mathbf{u}_s traveling wave in y and decaying as e^{-ax} into the domain.



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 μ , λ , and ρ constant.



 $\mu = 0.001, \, {\rm error} \, \, 10^{-4}$ need 34 seconds with 4th order scheme, 54 hours with 2nd order scheme.



Summary and future directions

- ▶ 4th order accurate non-dissipative difference scheme, L² norm stable with heterogeneous material and boundary conditions.
- 4th order in both space and time.
- Significant savings in computational resources.
- ► High order second derivative approximation of (µ(x)u_x)_x, with norm stable boundary closure, useful in other applications.
- To be implemented into the 3D WPP solver.
- To be used in new solver for source and material inversion, using adjoint wave propagation.

Reference

[1] B. Sjögreen and N.A.Petersson, A fourth order finite difference scheme for the elastic wave equation in second order formulation, Lawrence Livermore National Laboratory, LLNL-JRNL-483427, (to appear in J.Scient.Comput.).