

# Large-Scale Uncertainty and Error Analysis for Time-dependent Fluid/Structure Interactions in Wind Turbine Applications

## Background & Motivation

The design and operation of wind turbines is critically affected by uncertainties

- Different scenarios and drivers are considered for wind turbine design:
  - fatigue and extreme load survivability
  - aerodynamic performance and low environmental impact (noise)
- Two types of uncertainties are expected to affect the overall turbine behavior:
  - Natural stochastic (aleatory uncertainty): wind profile, dust/insect contamination, material properties, etc.
  - Physical model bias (epistemic uncertainty): laminar/turbulent transition, aero-structural coupling, wake turbulence, etc.

### Objectives of the project

- Develop, employ and critically compare novel methodologies for UQ in wind turbine applications
- Use gradient information and goal-oriented adaptivity to reduce the computational effort in evaluating statistics of the quantities of interest
- Distinguish and estimate the importance of numerical errors, aleatory and epistemic uncertainties
- Establish criteria for multi-fidelity simulations
- Disseminate UQ technologies to wind energy community



Horizontal Axis Wind Turbine      Vertical Axis Wind Turbine

## Uncertainty Quantification Methodology

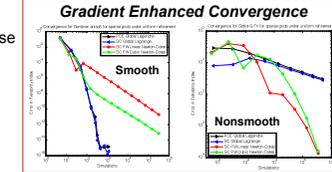
The use of gradient evaluations as an enhancement to classic stochastic collocation techniques is one of the main drivers of the algorithmic development

- Polynomial chaos and stochastic collocation methods based on sparse grids are available in DAKOTA
- Extensions to include gradient information have been developed
- For interpolants, generalized quadrature rules are defined...

$$\mu = \sum_{i=1}^N f_i w_i^{(1)} w_i^{(2)} w_i^{(3)} + \sum_{i=1}^N \frac{df_i}{dx_1} w_i^{(1)} w_i^{(2)} w_i^{(3)} + \sum_{i=1}^N \frac{df_i}{dx_2} w_i^{(1)} w_i^{(2)} w_i^{(3)} + \dots$$

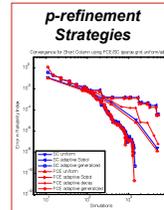
...as well as surface response reconstruction

$$f = \sum_{i=1}^N f_i H_i^{(1)}(x_1) H_i^{(2)}(x_2) H_i^{(3)}(x_3) + \sum_{i=1}^N \frac{df_i}{dx_1} H_i^{(1)}(x_1) H_i^{(2)}(x_2) H_i^{(3)}(x_3) + \sum_{i=1}^N \frac{df_i}{dx_2} H_i^{(1)}(x_1) H_i^{(2)}(x_2) H_i^{(3)}(x_3) + \dots$$



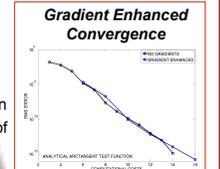
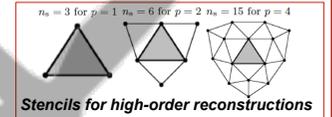
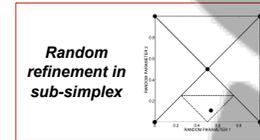
An additional thrust of the algorithmic work is the definition of p-/h-refinement strategies:

- Uniform: *isotropic* tensor/sparse grids
- Adaptive: *anisotropic* tensor/sparse grids
- Goal-oriented adaptive: *generalized* sparse grids



As a more flexible alternative to hypercube-based discretization of the parameter space we are considering the Simplex Stochastic Collocation method

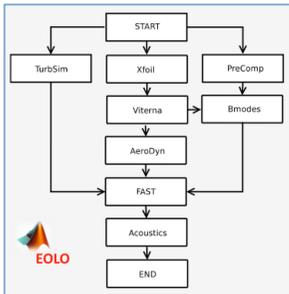
- Simplex elements discretization of probability space
- Delanuy triangulation and solution adaptive refinement
- Randomized sampling for efficiency in higher dimensional probability spaces
- High degree interpolation stencils
- Superlinear convergence for smooth responses
- Robust approximation of discontinuities using Local Extremum Diminishing (LED) limiter



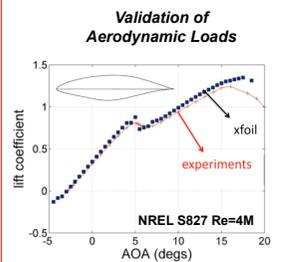
- Inclusion of gradient information has been completed
- Test case in 1D shows that gradient information at a node is equivalent to one additional function evaluation
- Extension to multi-dimensions ongoing with potential of extensive efficiency gain

## Multi-physics Wind Turbine Simulations

Wind Turbines are multi-physics devices, need comprehensive prediction tools



- We developed the EOLO framework
- Based on NREL tools
- Includes aerodynamics, structural dynamics, turbulent wind flows, noise
- The aerodynamic analysis is based on xfoil (low-fidelity flow prediction tool) rather than experimental correlation
- Blade stall and transition behavior are characterized using semi-empirical models (Viterna and e<sup>N</sup>, respectively)
- EOLO is driven by matlab and interfaced with Dakota



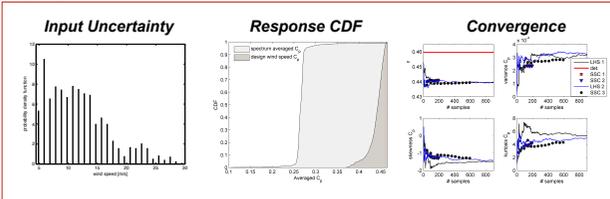
Prediction of the aerodynamic loads is a critical components

- EOLO predictions are compared to experiments for the NREL S827 airfoil, designed specifically for wind turbines
- In spite of the unorthodox aerodynamic behavior (kink in the lift curve) EOLO computations are in very good agreement with the measurements

## Uncertainty Quantification for Wind Turbine

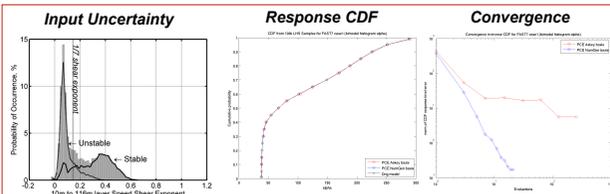
Evaluation of energy extraction and noise under uncertainty in wind condition (speed) and energy perturbations (dust, bugs)

- Input Uncertainty:** Speed velocity as a discrete histogram distribution and geometry perturbations as "assumed" continuous distributions (3 input variables).
- Output Metric:** Energy extraction (aerodynamic loading) and noise
- UQ Methods:** LHS and SSC (adaptive with 24/48 realizations added at each iteration)
- Response function evaluations:** 1k LHS samples for moments evaluation; up to 600 for SSC/PCE (in Fig. below SSC1 and SSC2 use 200 realizations and SSC3 uses 600)



Evaluation of fatigue under uncertainty in wind condition (shear)

- Input Uncertainty:** Speed shear exponent as continuous histogram distribution.
- Output Metric:** Blade root out-of-plane bending moment amplitude during steady limit cycle.
- UQ Methods:** LHS and PCE with Askey/Gauss-Patterson or numerically generated/Gauss using p-refinement (isotropic/anisotropic/generalized essentially equivalent for 1-D).
- Response function evaluations:** 100k LHS samples for PDF/CDF eval (truth or approx); up to 255 for Askey PCE (level w=7); up to 21 for NumGen PCE (level w=10).



## Towards Multi-fidelity Modeling

As a step towards high fidelity aero-mechanics simulations of (vertical-axis) wind turbines, we investigated the use of moving meshes and Time-Spectral methods

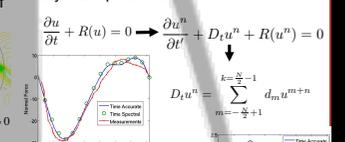
The sliding mesh technology being evaluated is based on a novel DG formulation built upon DOE's ASC SIERRA T/H CVFEM code base

Numerical fluxes are evaluated on each of the "owing" blocks

$$\frac{\partial u}{\partial t} + R(u) = 0 \rightarrow \frac{\partial u^n}{\partial t} + D_t u^n + R(u^n) = 0$$

$$D_t u^n = \sum_{m=-\frac{N}{2}+1}^{N-\frac{N}{2}-1} d_{m,n} u^{m+n}$$

The time-spectral method takes advantage of temporal periodicity and replaces the time-marching algorithm with a Fourier-based representation (but in the time-domain) that can be solved as a pseudo steady-state problem.



This allows for large savings in computational cost and feasible adjoint solutions. Figures compare 128 steps/rev time marching vs 16 time-spectral instances.

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