

High Performance Computing for Situational Awareness in Power System Grid

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Power System Simulation Complexity

Element

Transmission-
level Simulation

Components*

Generation

$\sim 10^2$

Transmission

$\sim 10^4$

$\sim 10^3$

Substations

$\sim 10^4$

Distribution Feeders

$\sim 5 \times 10^4$

Customer Meters

$\sim 10^4$

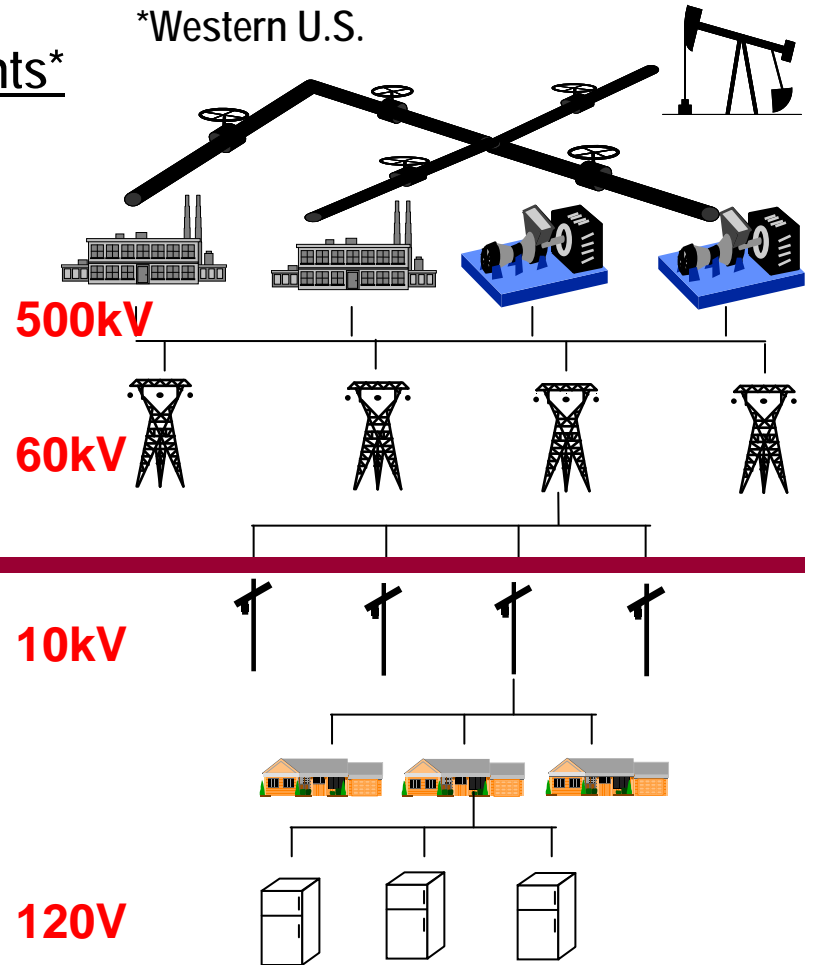
$\sim 10^7$

Appliances/Equipment

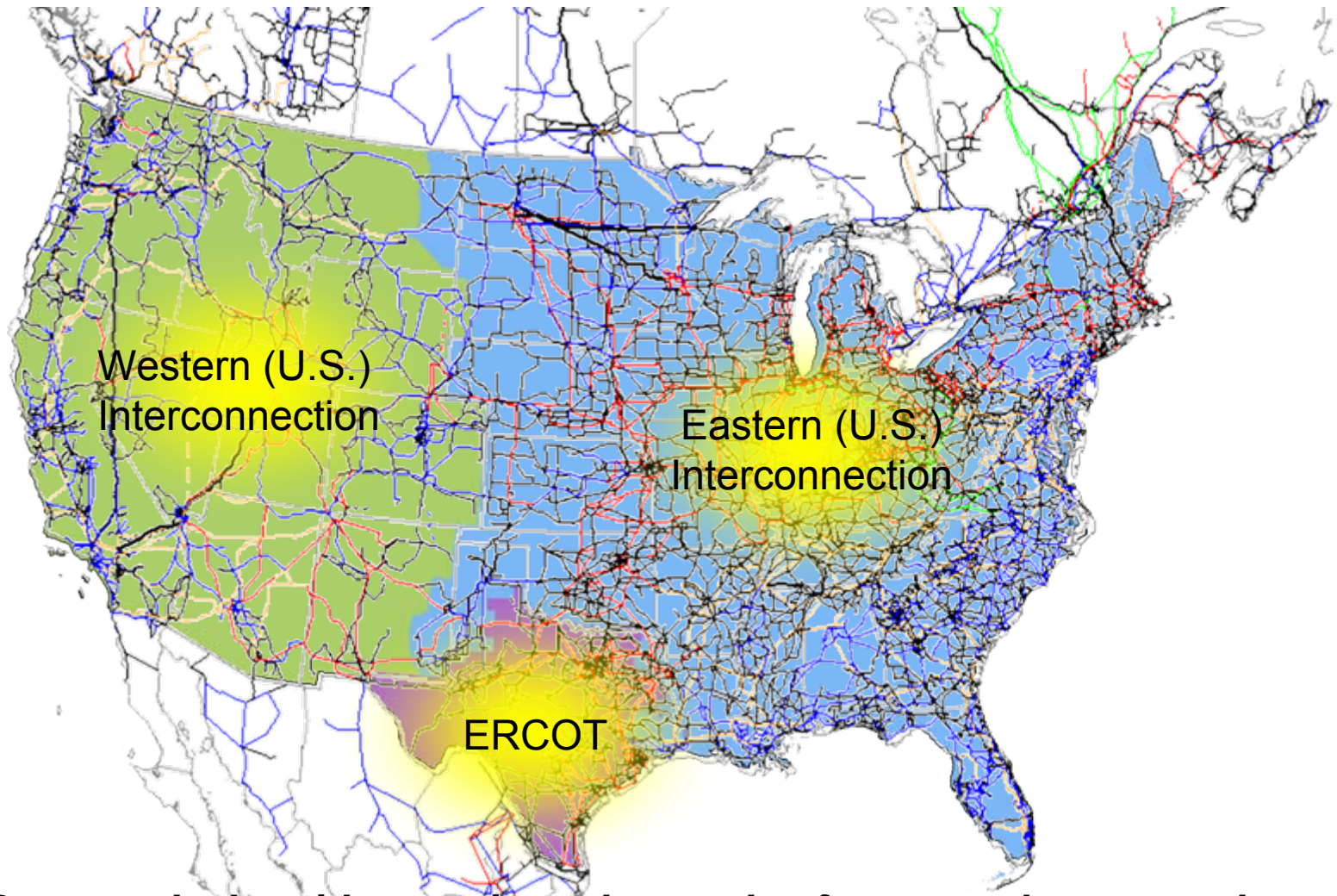
$\sim 5 \times 10^8$

Distribution-
level Simulation

*Western U.S.

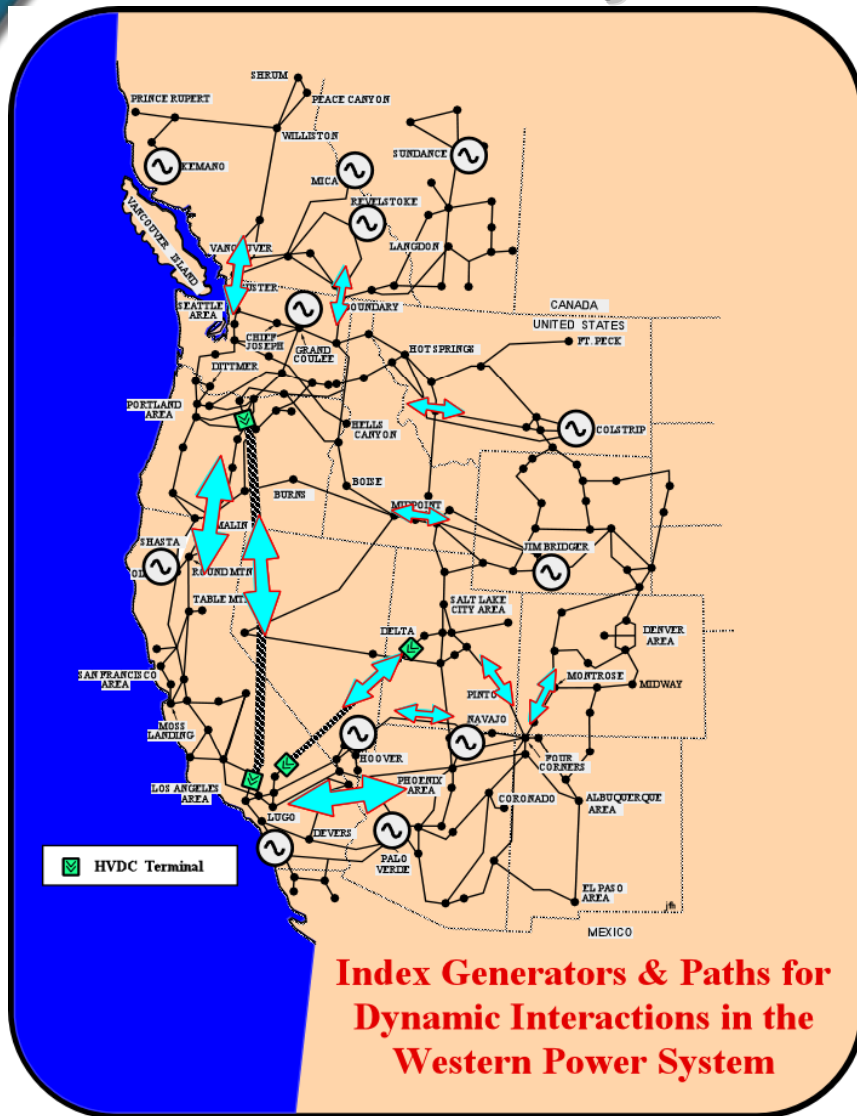


Situational Awareness in Power Grid Is An Interconnection-Scale Issue



But ... today's grid operations data and software can't support the real-time analysis required for dynamic situational awareness of such large and complex systems

Power System Dynamic Model



Source: J. Hauer. 2004

Differential Algebraic Equations

$$\begin{cases} \frac{dx}{dt} = f(x, y) & \text{Dynamic models} \\ 0 = g(x, y) & \text{Power flow model} \end{cases}$$

x : State Variables

y : Algebraic Variables

WECC Power System

2,700 generators

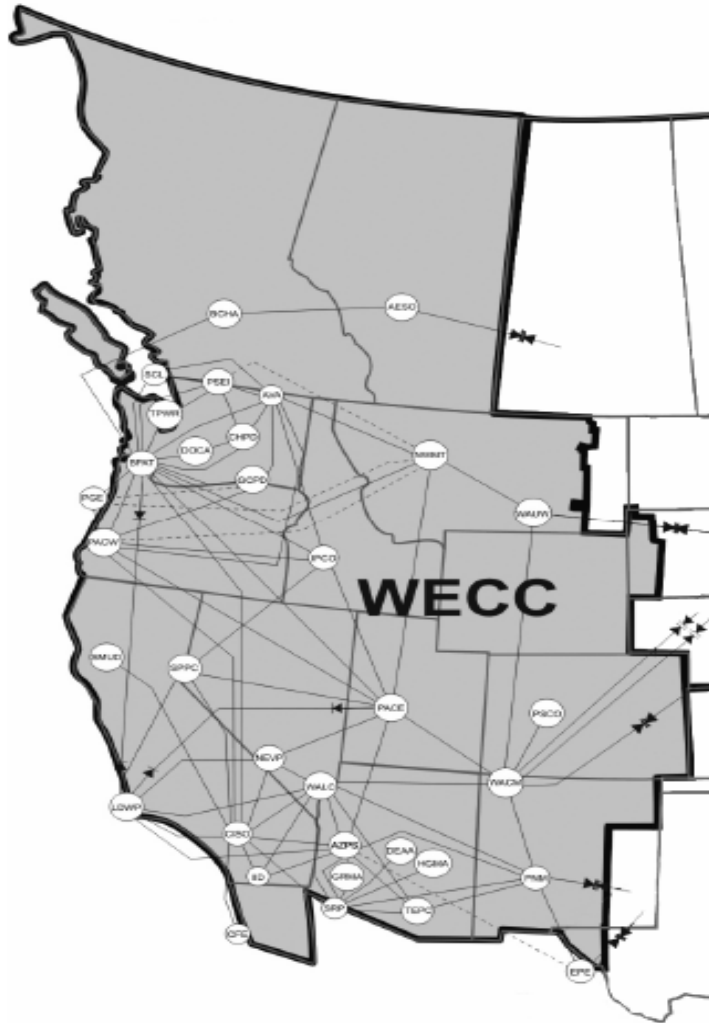
3rd-order model

8,100 state variables

Plus other dynamic models

**State Variables:
an order of 10^4**

Steady-State Model



Power Flow Equation

$$0 = g(V, \theta, P, Q)$$

Breaker-Oriented Model (EMS) WECC Power System

10,000 buses

16,000 lines

2,700 generators

20,000 unknowns in power flow model

40,000 analog measurements

100,000 digital measurements

State Variables:

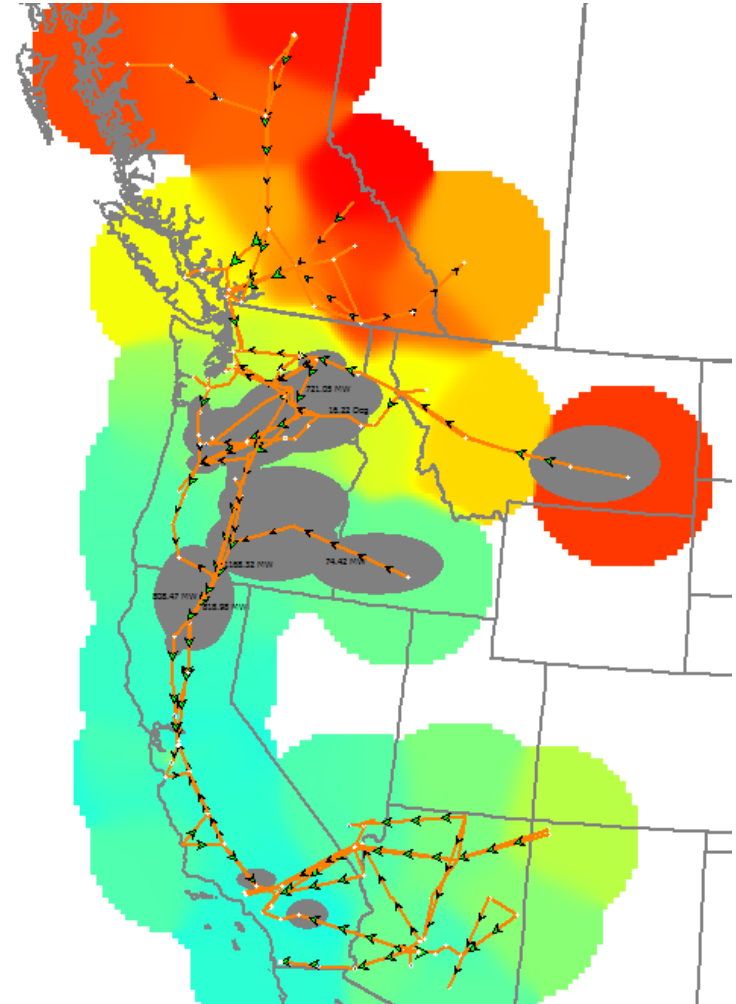
An order of 10^4 (PF) & 10^5 (EMS)

Does not seem that bad but...

**For effective decision support we
need to run analysis in seconds!!**

Telemetry Data

- ▶ High-Level Real-Time View of WECC System
 - 500 kV AC
 - 367 lines
 - 167 buses
 - ~70 PMUs
- ▶ Data Volume and Rates
 - SCADA system: ~4 seconds
6 GB/day
 - Phasor system: 1/30 second
5 GB/day → 3 TB/day



Electricity Infrastructure Operations Center

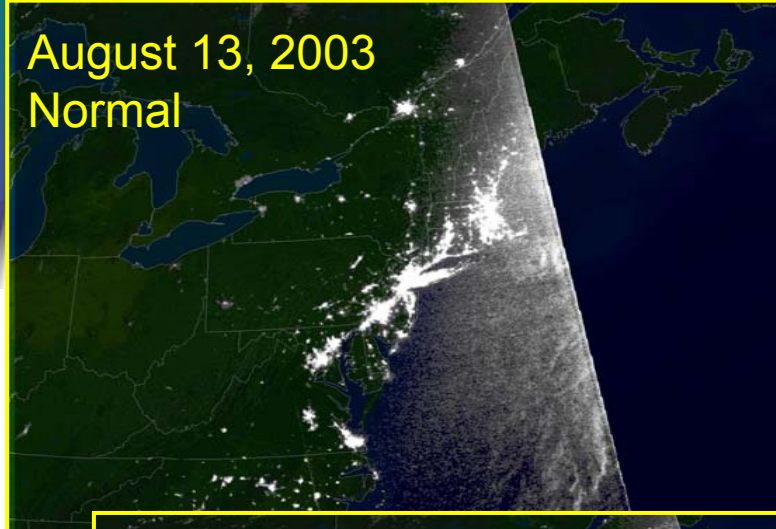
**Pacific Northwest
National Laboratory**
Operated by Battelle for the
U.S. Department of Energy



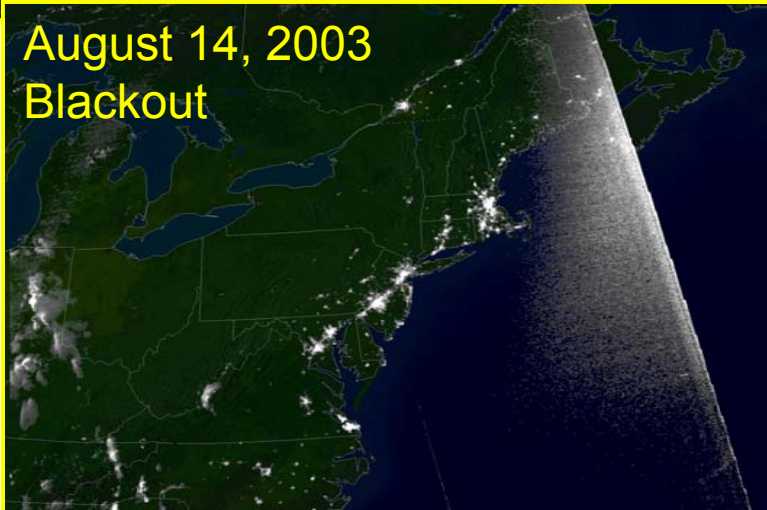
Energy Science and Technology Directorate

Blackout of 2003

August 13, 2003
Normal

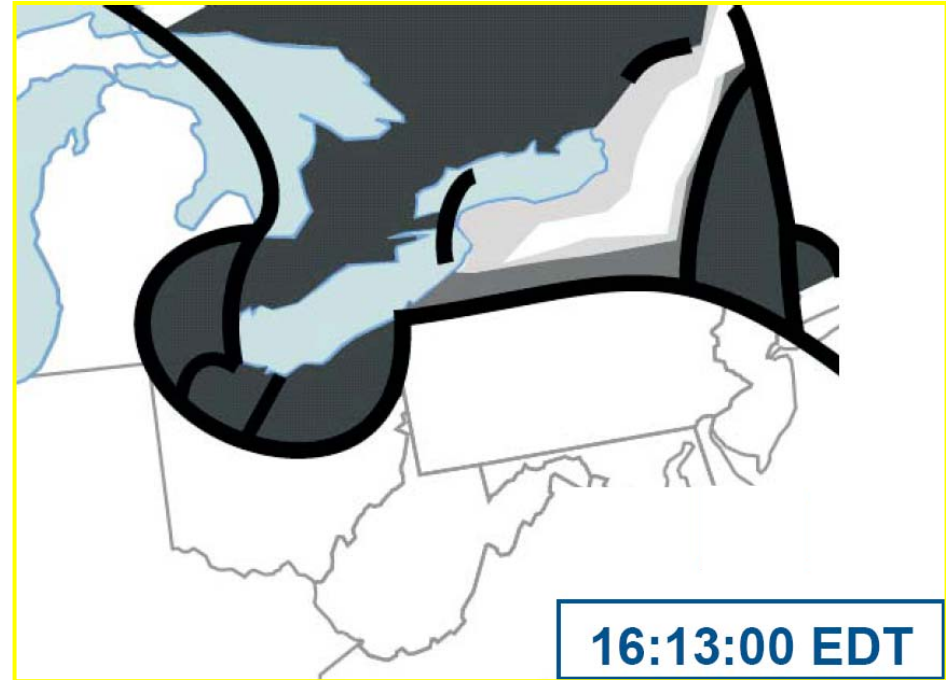


August 14, 2003
Blackout



Source: NOAA/DMSP

Source: Blackout Final Report

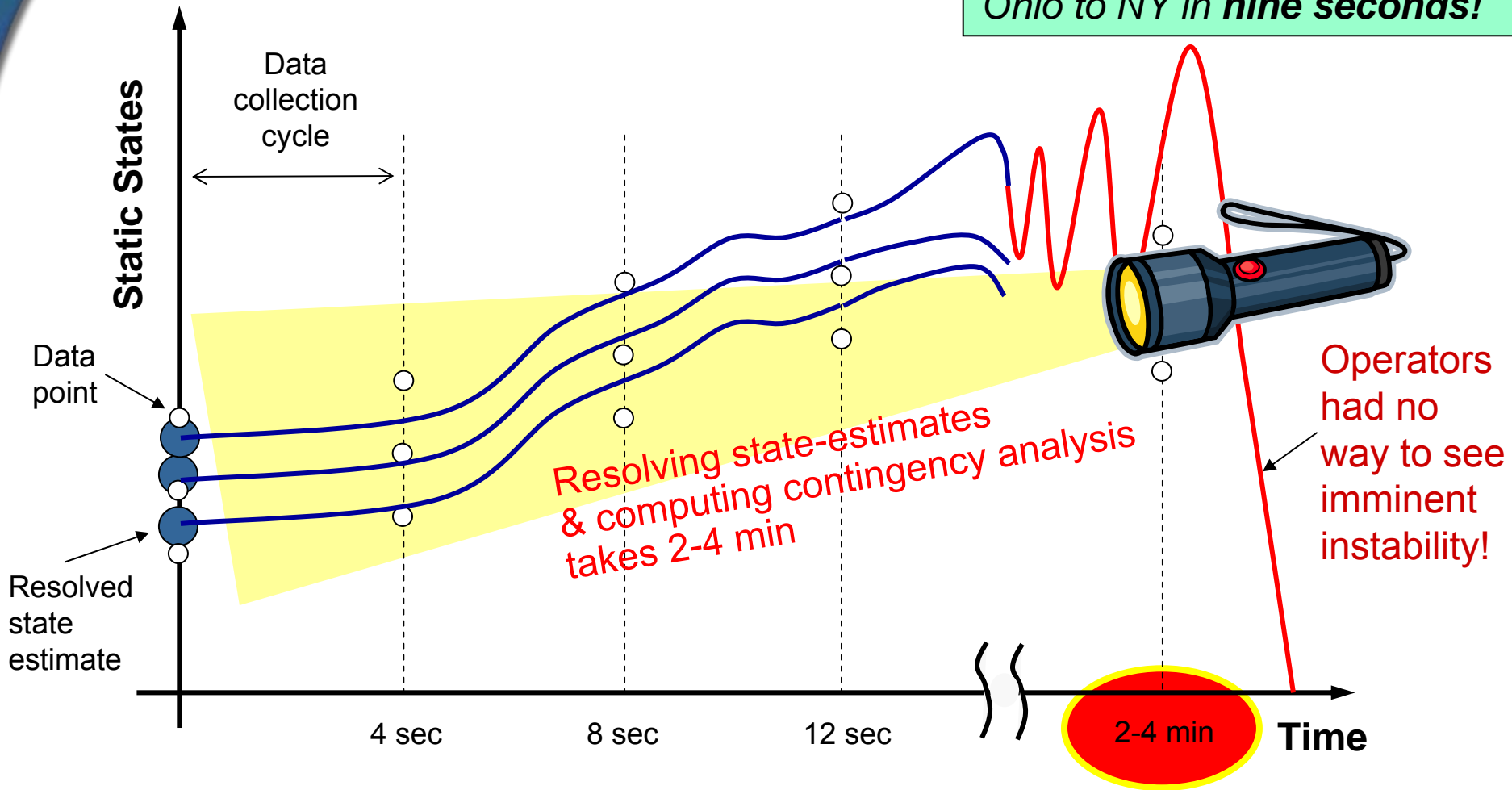


- > **Lack of situational awareness!**
- > **How to improve situational awareness?**

Computational Problem

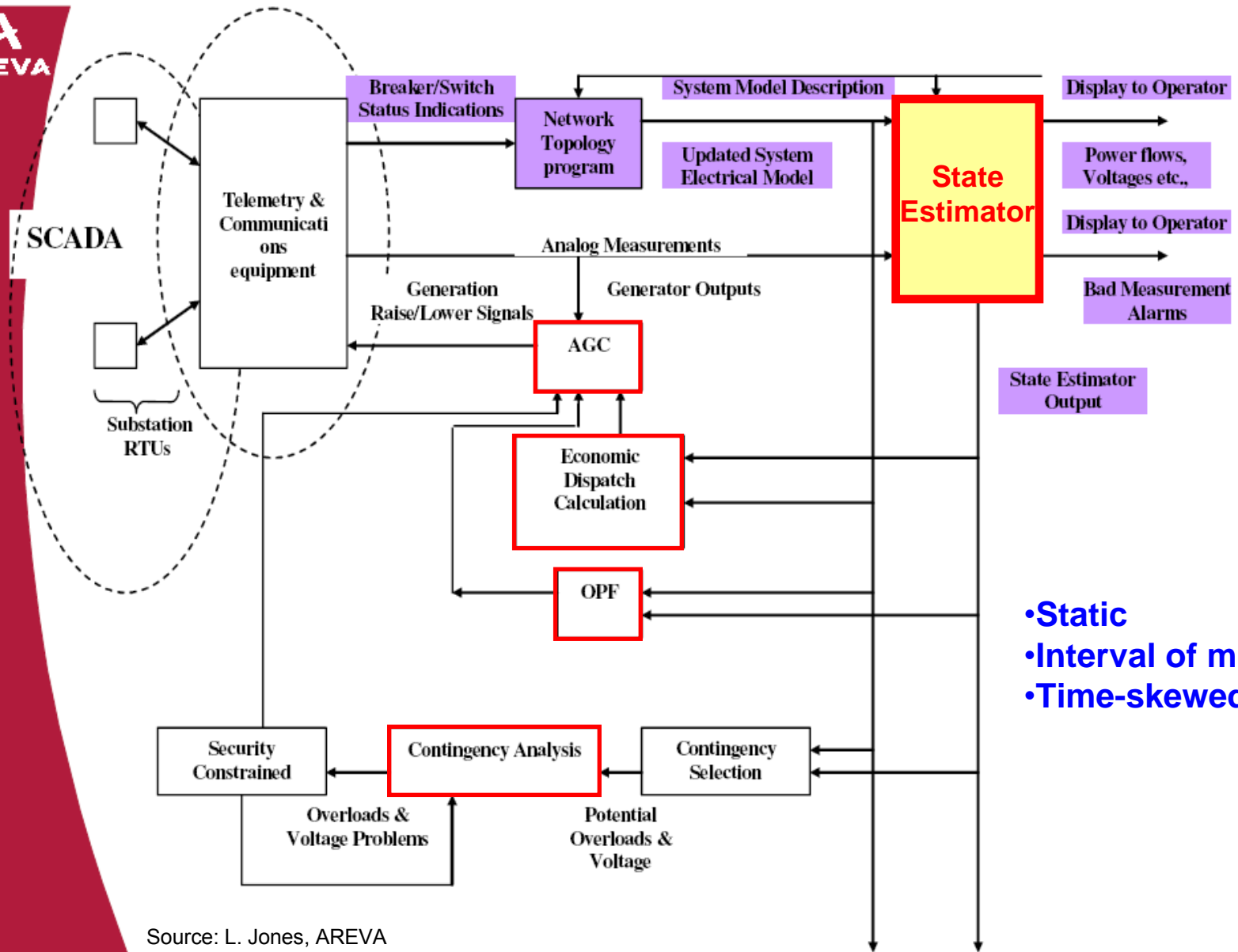
Point-of-departure: Static State Estimation

Once the cascade began, the 2003 blackout swept from Ohio to NY in **nine seconds!**



State Estimation

Core of Power System Monitoring and Operations



- Static
- Interval of minutes
- Time-skewed data

Weighted Least Square State Estimation

- ▶ Nonlinear Optimization Problem
 - Maximum Likelihood Weighted Least Squares (WLS) method
 - Weighted Least Absolute Value (WLAV)
 - LP problem (Simplex, Karmarkar)
- ▶ Our focus is on the WLS method
 - Iterative procedure requires a solution of a large sparse set of linear equations $A\Delta x = b$ obtained through linearization in each iterative step of Newton-Raphson
- ▶ The main computational effort is the solver of linear equations – highly irregular sparsity patterns
 - *Direct Methods give fast solution on a serial processor but offer limited coarse-grain parallelism*
 - *Iterative Methods are slower on serial processor but offer higher coarse-grain parallelism*

WLS Method

$$z = h(x) + e$$

Truncated Taylor series expansion:

$$z = h(x^*) + H(x^*)\Delta x + e$$

$$H = \left. \frac{\partial h(x)}{\partial x} \right|_{x=x^*}$$

$$\text{Min } (z - h(x))^T R^{-1} (z - h(x))$$

$$x^{k+1} = x^k + A (z - h(x^k))$$

$$A = [H^T R^{-1} H]^{-1} H^T R^{-1}$$

R – noise covariance matrix

z – measurement vector

H – Jacobian matrix of h

x – state vector (voltage & angle)

h – nonlinear function

Architectural Considerations

- ▶ Characteristic of the problem
 - need for near real-time operation
 - Problem sizes not very big + fine grain computations
 - Irregular communication
- ▶ Focus on shared-memory multiprocessor systems rather than on clusters
- ▶ SGI Altix with 128 1.5 GHz Itanium-2 CPUs
 - Shared memory programming models
 - Pthreads, OpenMPI, System V shared memory
 - Standard MPI distributed memory programming model
- ▶ Cray MTA-2 multithreaded system



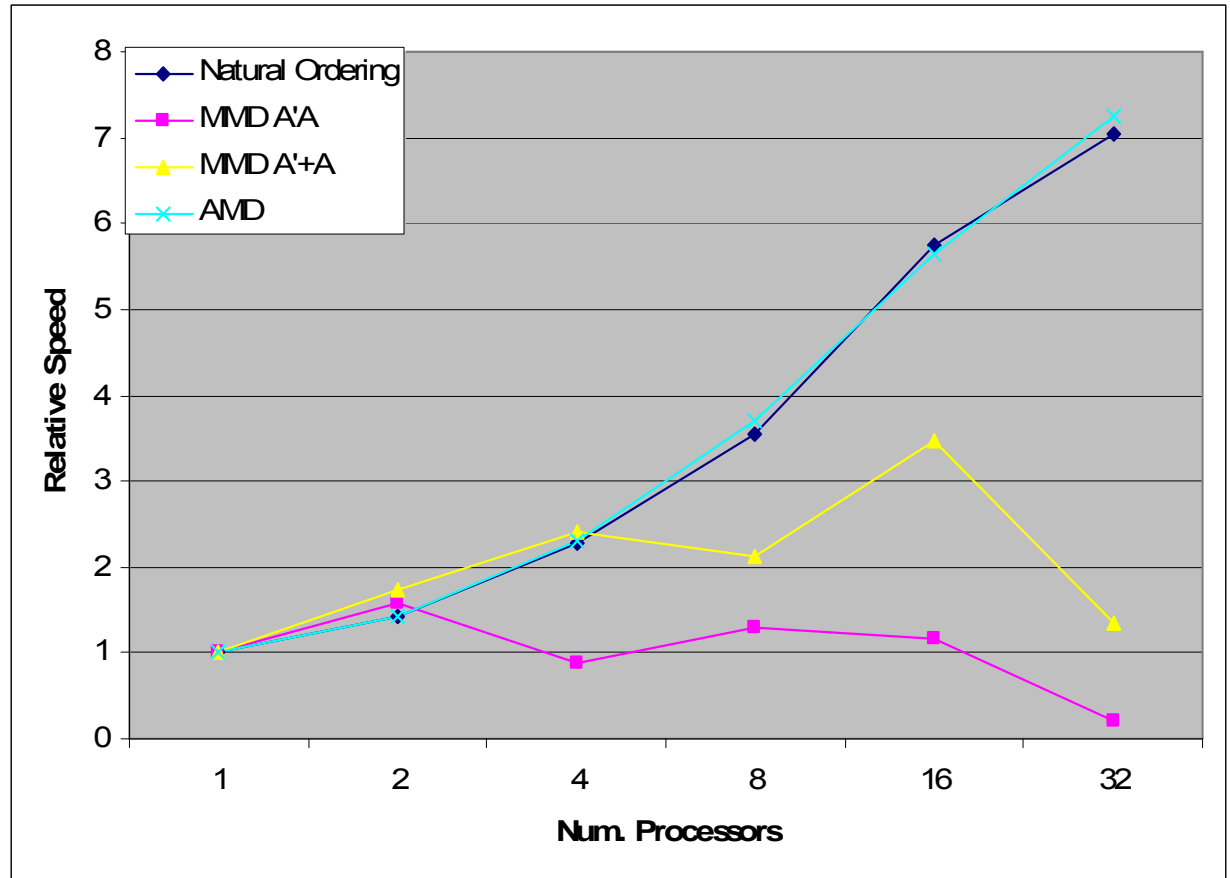
Parallel WLS State Estimation

- ▶ Critical to accelerate solution of the Weighted Least Square Algorithm
 - Solve very large problems >10,000-100,000 bus systems
 - Exploit emerging systems with multi-core processors
 - Rely of efficiency of shared memory communication
 - Such systems will be broadly available and affordable to industry
- ▶ Solution of Sparse Linear System of Equations is the core computational kernel in the WLS algorithm
- ▶ Deployed State-of-the-art Direct Solvers
 - SuperLU is frequently used for solving PDEs
- ▶ SGI Altix shared memory system
 - Multithreaded version of SuperLU
 - MPI version slower
 - SGI MPI (shared memory)

# Processors vs. Programming Model	1	2	4
MT-SuperLU	0.209s	0.147s	0.169s
MPI-SuperLU	1.106s	1.102s	1.102s

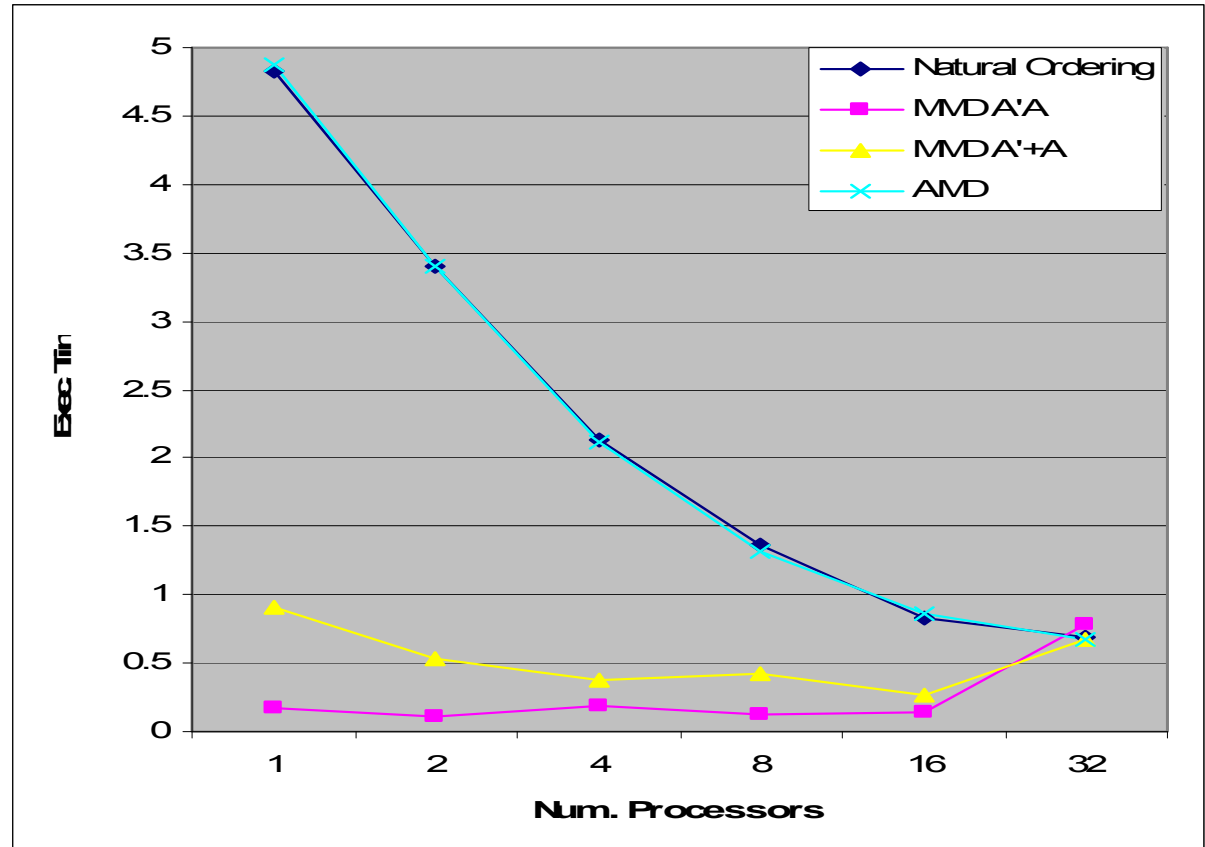
Ordering Scheme and Speedup

Approximate Minimum
Degree Produces
Best Speedups !



Ordering Scheme and Time to Solution

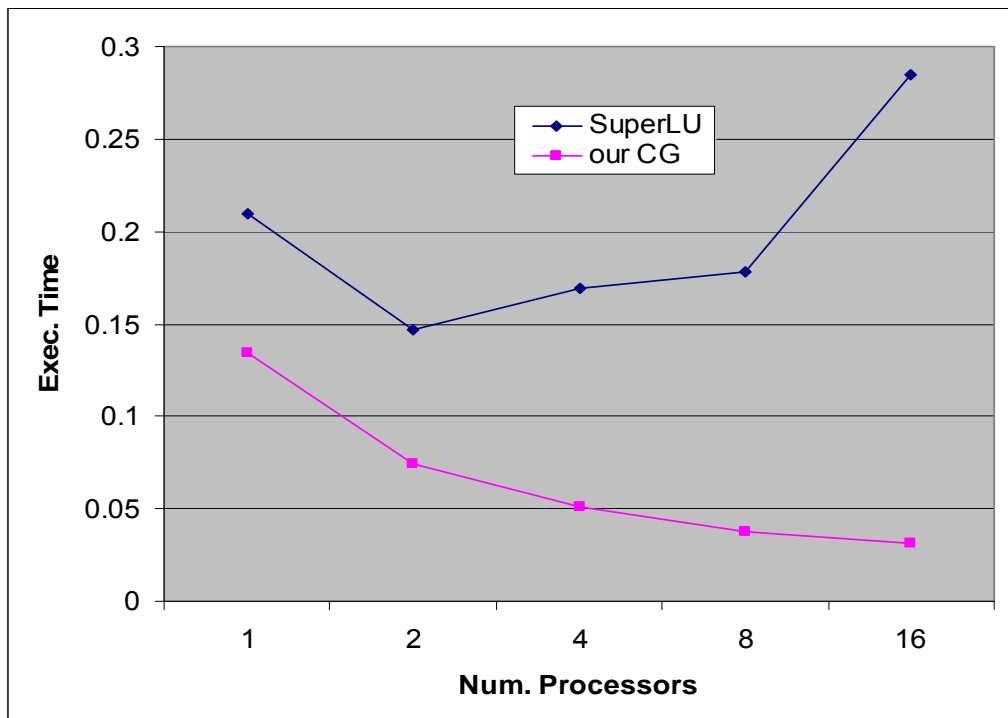
Multiple Minimum Degree
Is FASTEST
BUT
Not Much Faster Than
Serial Algorithm



Conjugate Gradient in State Estimation

► Shared memory version of Conjugate Gradient

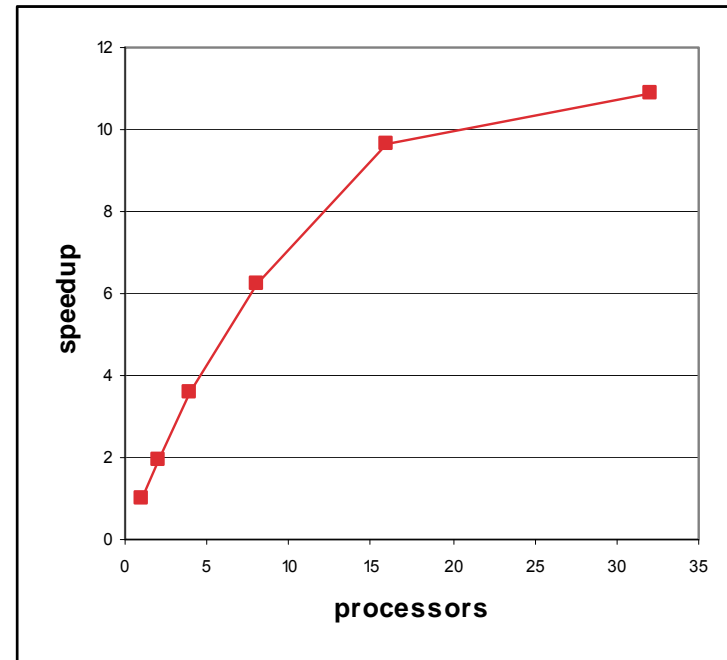
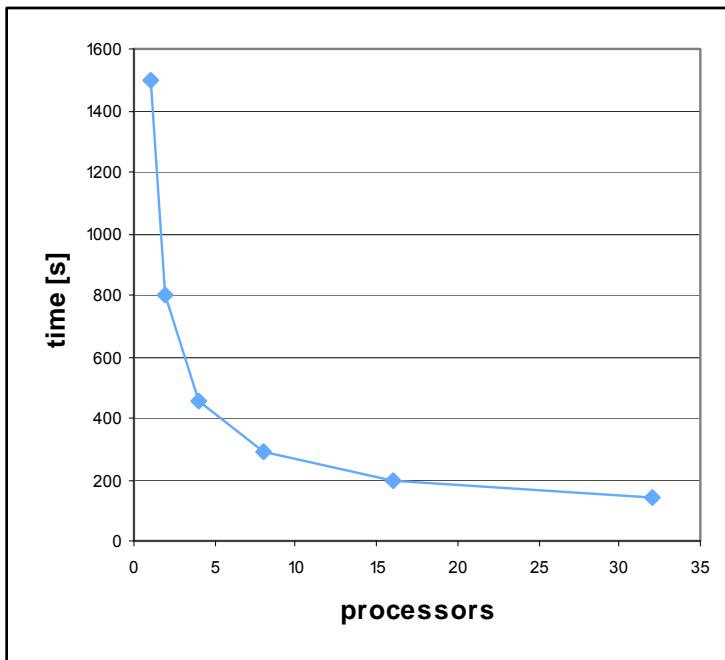
- Load balancing in the sparse matrix-vector product
- Experimental evaluation on the SGI Altix shared memory system
- Better **performance** and **scalability** compared to SuperLU package (both **multithreaded** and MPI versions)



Paper at 2006 IEEE PES General Meeting. Montreal, June 2006: Nieplocha J, A Marquez, V Tipparaju, D Chavarría-Miranda, RT Guttromson, and Z Huang. "Towards Efficient Parallel State Estimation Solvers on Shared Memory Computers"

Full State Estimation on Cray MTA-2

- ▶ Cray MTA-2 parallel multithreaded architecture
- ▶ Parallelization of the full WLS State Estimation Code done based on Cray language directives
- ▶ WECC model simplified: ~14000 buses



Challenges in Dynamic State Estimation

- ▶ **Non-linearity of the model**
- ▶ **Large set of ODEs and Algebraic Equations**
- ▶ **Sparsity**
- ▶ **Real-time operation requirements**
- ▶ **Need solvers effective for the power system area**
- ▶ **Data management for telemetry data**
- ▶ **We are developing Extended Kalman Filter**

Added Complexity of Problem Scales

▶ Data Volume/Rate and State Estimation Requirements

- SCADA: ~4 seconds → 100 time speedup
6 GB/day
- Phasor data: 1/30 second → 10^4 time speedup
5 GB/day → 3 TB/day

▶ Problem Size

- Currently contingency analysis: N-1 only = ~20000 cases, BPA runs only 500 select cases every 5 minutes.
- N-2 = $\sim 10^8$; N-3 = $\sim 10^{12}$; N-4 = $\sim 10^{17}$ → **a Peta-scale problem**

▶ Other Factors

- Weather – load, wind power
- Environment
- ...

**Dozens of components
went out of service
during 2003 blackout!!!**

▶ It can not be solved with hardware and software currently used. We must explore advanced computing

Outlook into the Future with HPC Power System Computation

▶ Better Models and Simulation

- Model identification/validation/enhancement
- Topology/parameter estimation and identification
- Faster dynamic simulation

▶ Better Monitoring

- Dynamic stability monitoring
- Response adequacy measurement and monitoring
- Power quality monitoring/enhancement

▶ Better Control

- SPS/RAS design and operation
- Reactive power coordination
- Resource adequacy, commitment & scheduling
- Fault/outage management

Questions?

